

# Determinant and recurrent mapping

## A. The Ikeda map

The Ikeda map[52] is characterized by a nonlinear system,

$$f(x_1, x_2) = \begin{cases} f_1(x_1, x_2) \\ f_2(x_1, x_2) \end{cases}$$

where coordinate functions are given by

$$f_1(x_1, x_2) = R + C_2(x_1 \cos (C_1 - C_3/(1 + x_1^2 + x_2^2)) - x_2 \sin (C_1 - C_3/(1 + x_1^2 + x_2^2))),$$

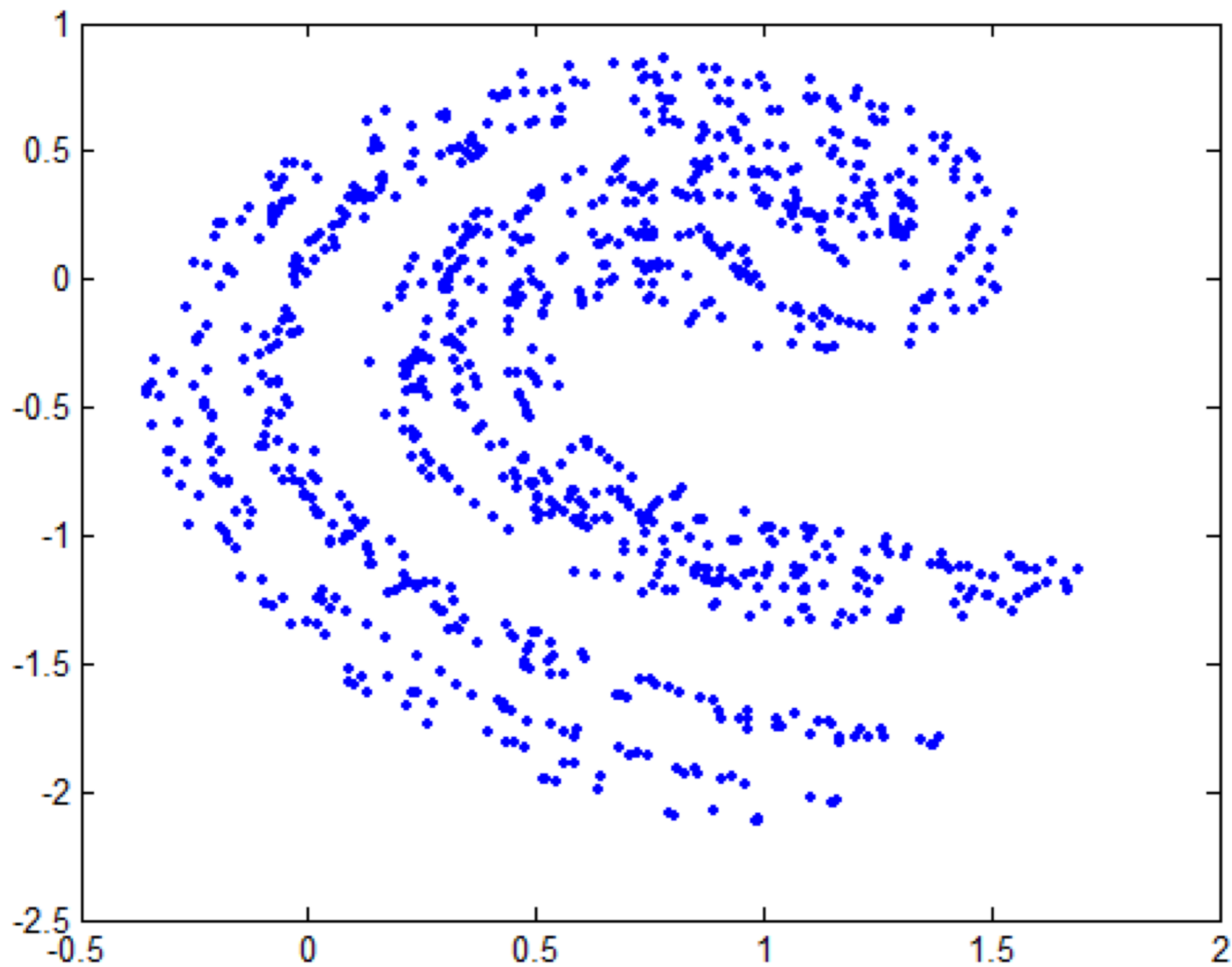
$$f_2(x_1, x_2) = C_2(x_1 \sin (C_1 - C_3/(1 + x_1^2 + x_2^2)) + x_2 \cos (C_1 - C_3/(1 + x_1^2 + x_2^2))),$$

The parameters are given by  $R = 1$ ,  $C_1 = 0.4$ ,  $C_2 = 0.9$ , and  $C_3 = 6$ .

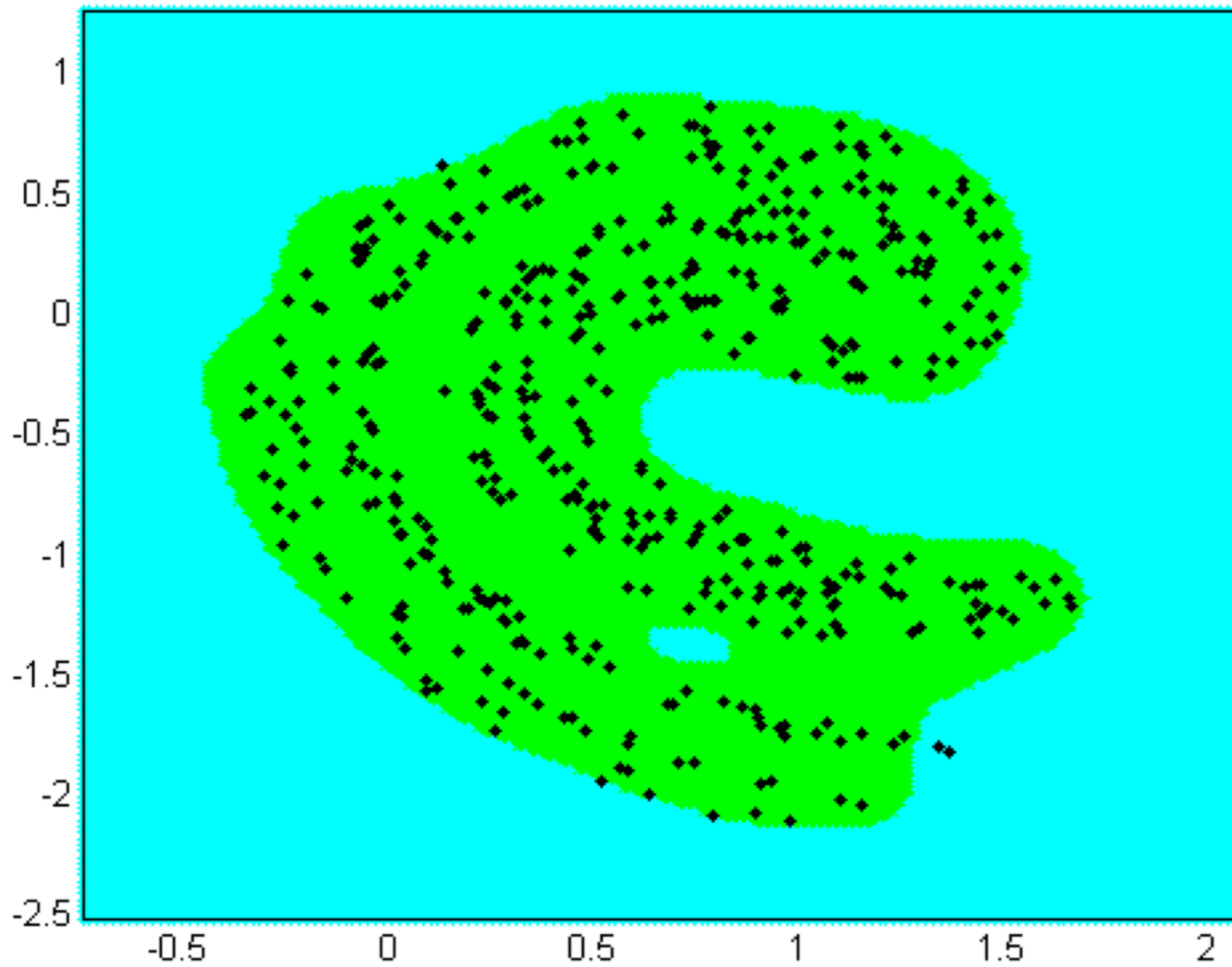
Let  $\mathbf{x}[n] = (x_1[n], x_2[n])$  and  $\mathbf{x}[0]$  denote a random initial condition. The Ikeda time series is generated by the first-order recursive function,

$$\mathbf{x}[n + 1] = f(\mathbf{x}[n]). \tag{1}$$

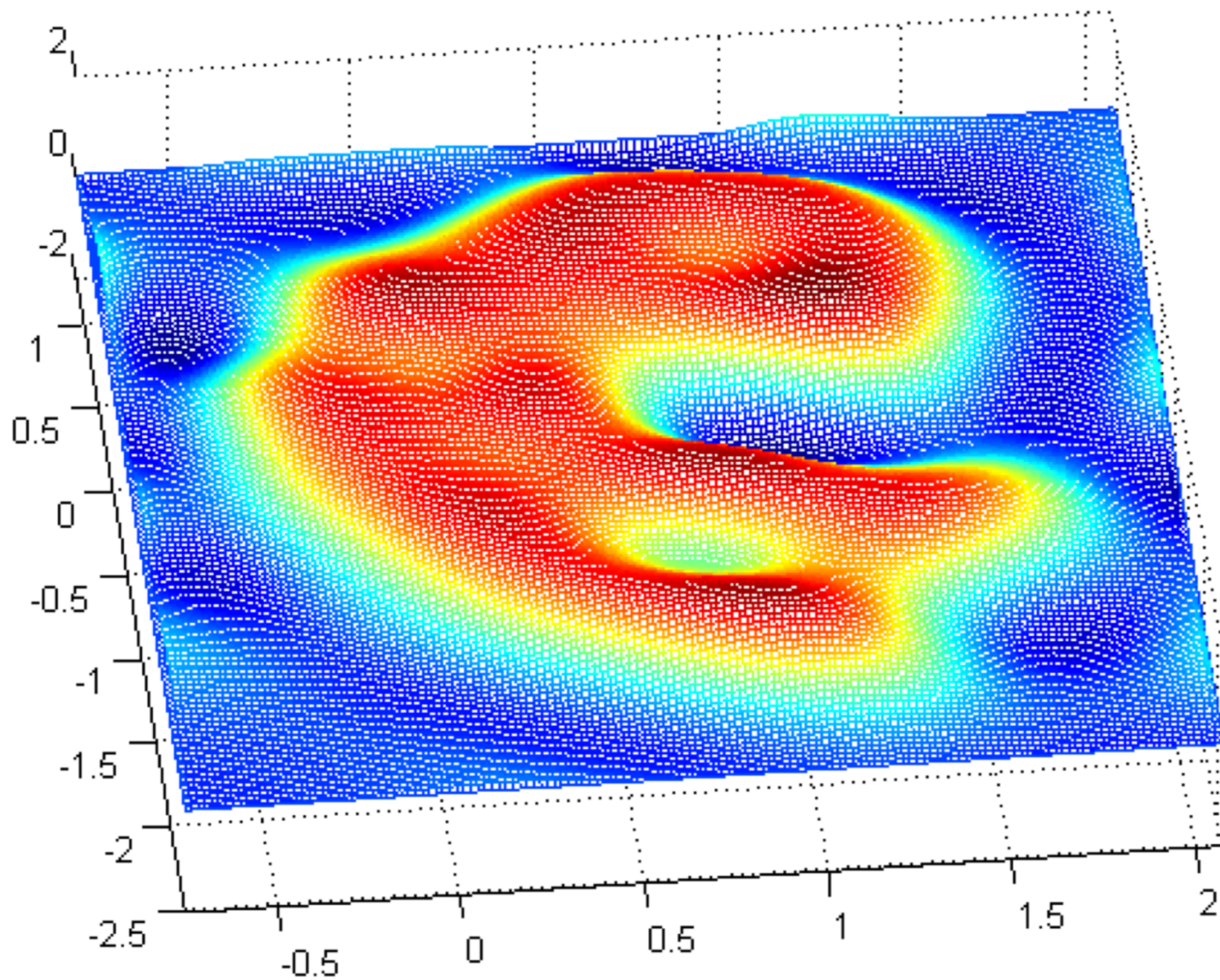
ikedada time series

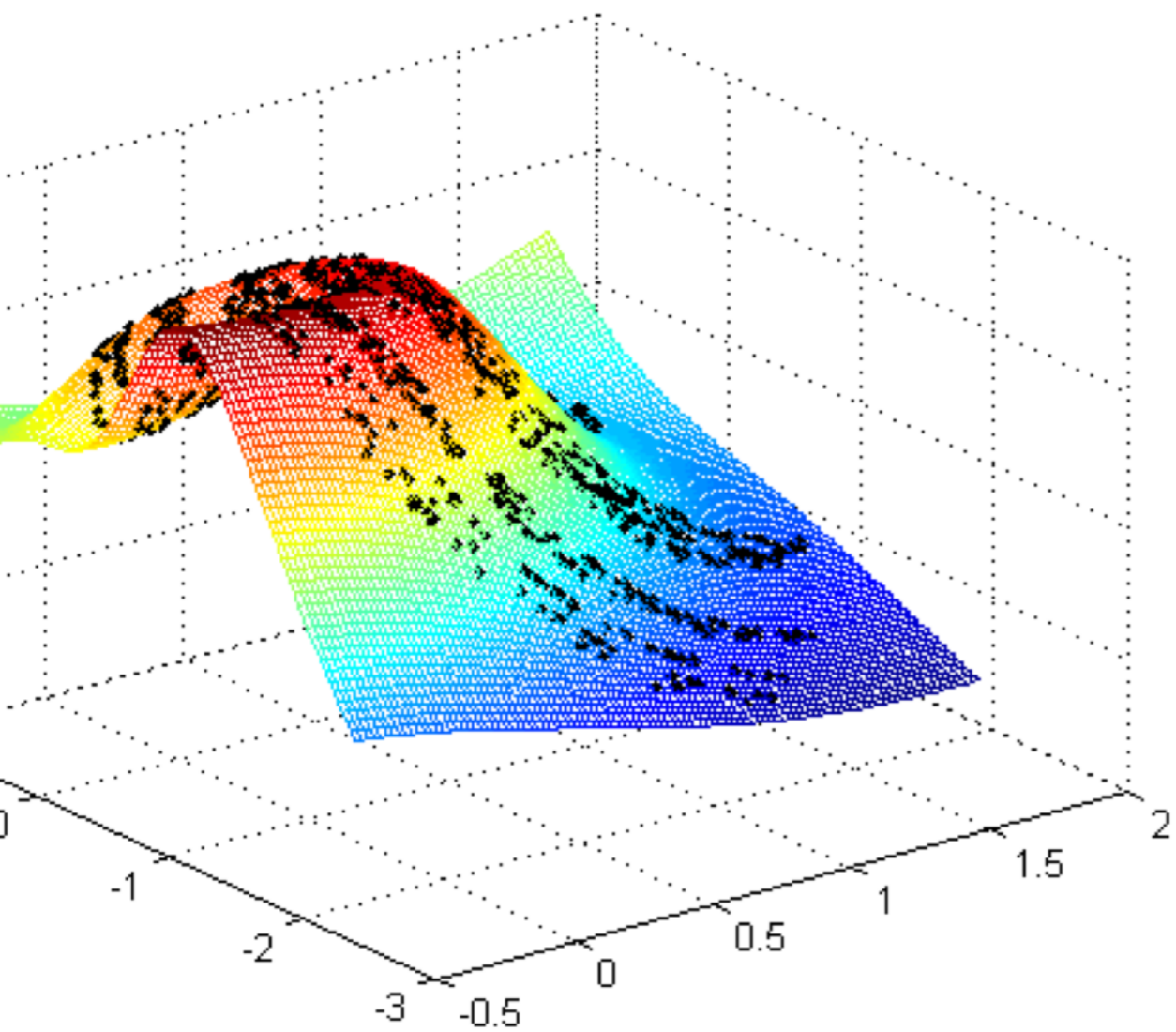


# Density support

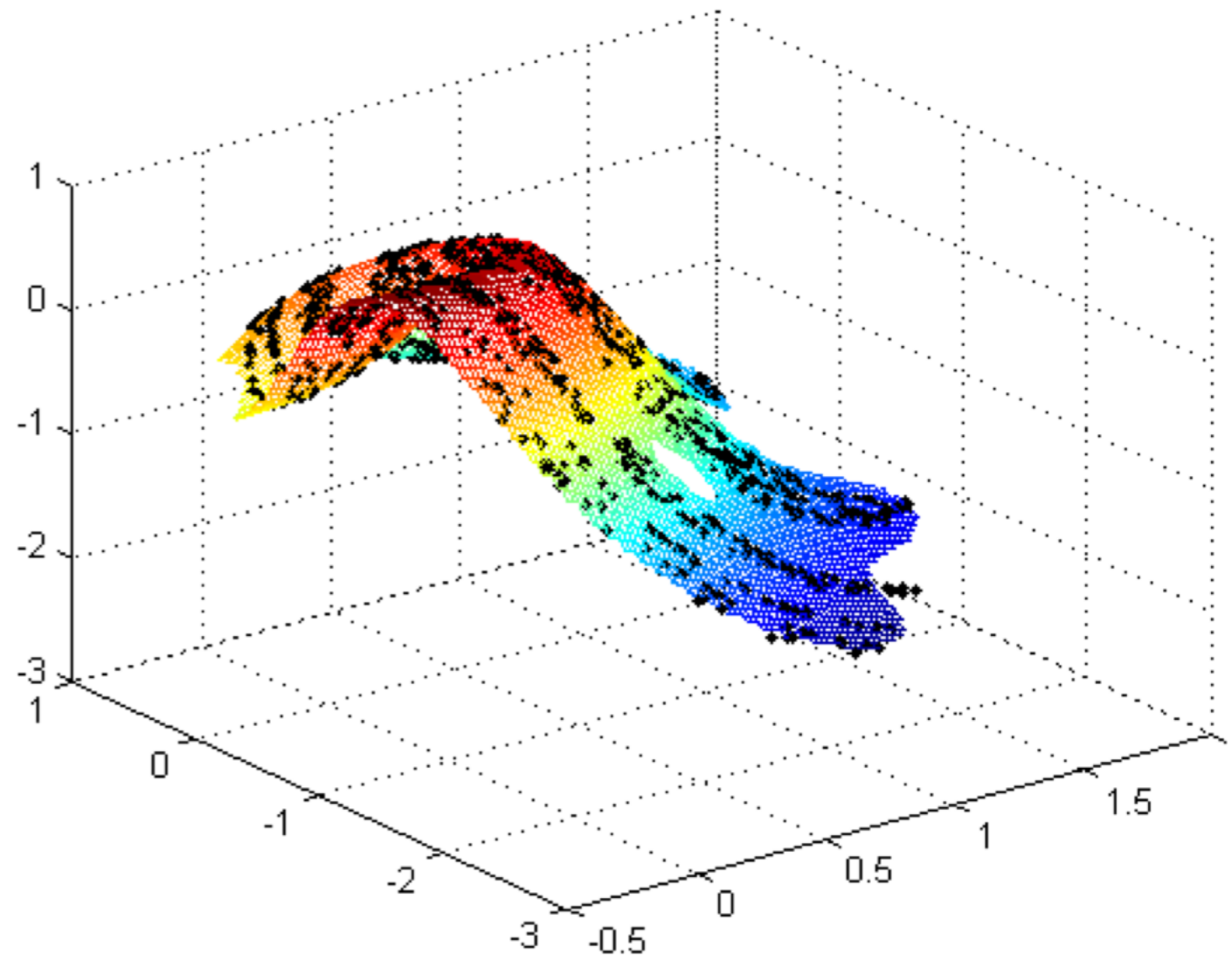


# Support indicator function



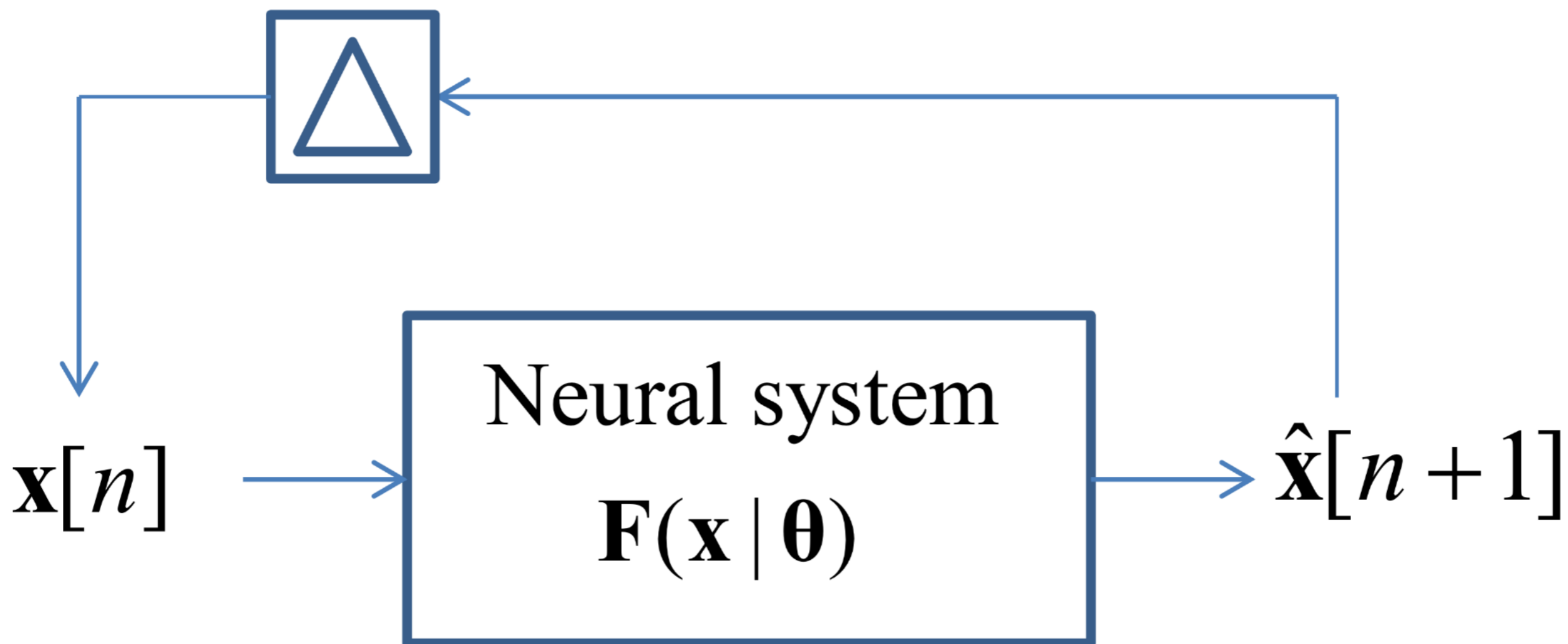


$$f_2(x_1, x_2)$$



$$F_2(x_1, x_2 | \theta_2)$$

MSE : Training error : 8.5348e-008  
Testing error : 6.3944e-007





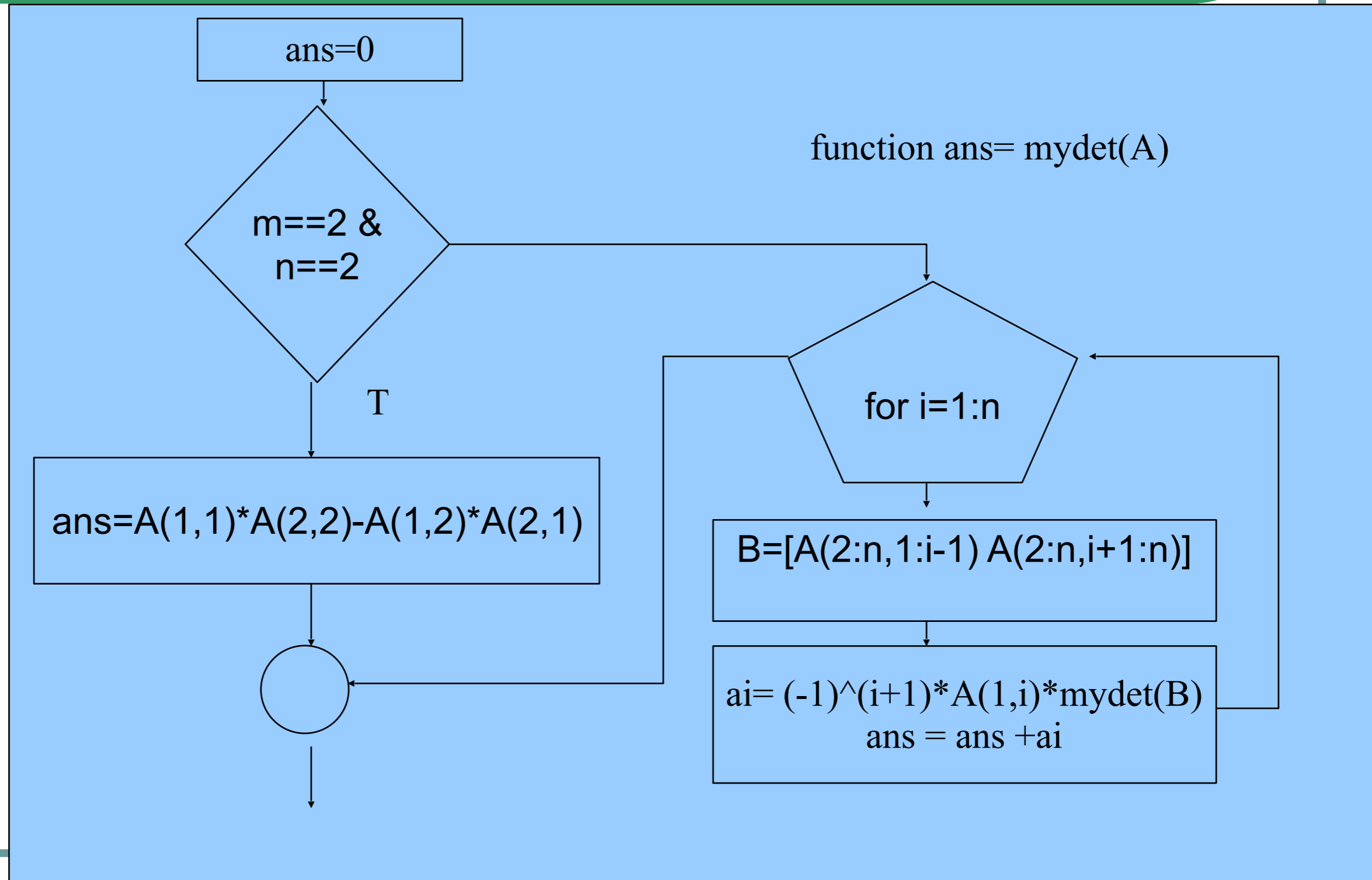


# Recurrent relation of Laplacian expansion

- $\det(A)$  is decomposed to  $n$  sub-tasks
- Each calculates determinant of an  $(n-1)$ -by- $(n-1)$  matrix  $\tilde{A}_{1i}$
- The problem size is reduced from  $n$  to  $n-1$

$$\text{Det}(A) = \sum_{i=1}^n (-1)^{i+1} a_{1i} \det(\tilde{A}_{1i})$$

# Recursive programming based on Laplacian expansion



# Drawbacks

- Computational complexity,  $O(n!)$
- Time consuming
- Memory consuming
- If  $n > 10$ , it results in intolerant computing time to evaluate determinant by recursive programming.
- An improvement by Bareiss's standard fraction free Gaussian elimination

# Bareiss's standard fraction free Gaussian elimination

Bareiss' standard fraction free Gaussian elimination (Bareiss, 1968).

$$\begin{aligned}A_{0,0}^{(-1)} &= 1, \\A_{i,j}^{(0)} &= A_{i,j}, \text{ for } 1 \leq i \leq n, 1 \leq j \leq m, \\A_{i,j}^{(k)} &= \frac{A_{k,k}^{(k-1)} A_{i,j}^{(k-1)} - A_{i,k}^{(k-1)} A_{k,j}^{(k-1)}}{A_{k-1,k-1}^{(k-2)}}, \text{ for } 1 \leq k < n, k < i, j \leq m.\end{aligned}$$

It is well known that

$$A_{i,j}^{(k)} = \begin{vmatrix} A_{1,1} & \cdots & A_{1,k} & A_{1,j} \\ \vdots & & \vdots & \vdots \\ A_{k,1} & \cdots & A_{k,k} & A_{k,j} \\ A_{i,1} & \cdots & A_{i,k} & A_{i,j} \end{vmatrix}.$$

Thus when  $m = n$ ,  $\det(A) = A_{n,n}^{(n-1)}$ , and when  $A = \begin{pmatrix} M & b \\ I & 0 \end{pmatrix}$ , for square

```
[N,M]=size(A);  
a=zeros(N,N,N);
```

for  $1 \leq k < n, k < i, j \leq m.$

```
for k=1:N  
for i=k+1:N  
for j=k+1:N
```

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```
end
end
end
```

```

if k==1
a(i,j,k)=A(k,k)*A(i,j)-A(i,k)*A(k,j);
end

```

```

if k==2
a(i,j,k)=(a(k,k,1)* a(i,j,1)-a(i,k,1)* a(k,j,1))/A(k-1,k-1);
end

```

```

if k>2
a(i,j,k)=(a(k,k,k-1)* a(i,j,k-1)-a(i,k,k-1)* a(k,j,k-1))/a(k-1,k-1,k-2);
end

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a=zeros(N,N,N);
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    if k==1
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    end
    if k==2
        a(i,j,k)=(a(k,k,1)* a(i,j,1)-a(i,k,1)* a(k,j,1))/A(k-1,k-1);
    end
    if k>2
        a(i,j,k)=(a(k,k,k-1)* a(i,j,k-1)-a(i,k,k-1)* a(k,j,k-1))/
a(k-1,k-1,k-2);
    end
end
end
end
a(N,N,N-1)

```

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