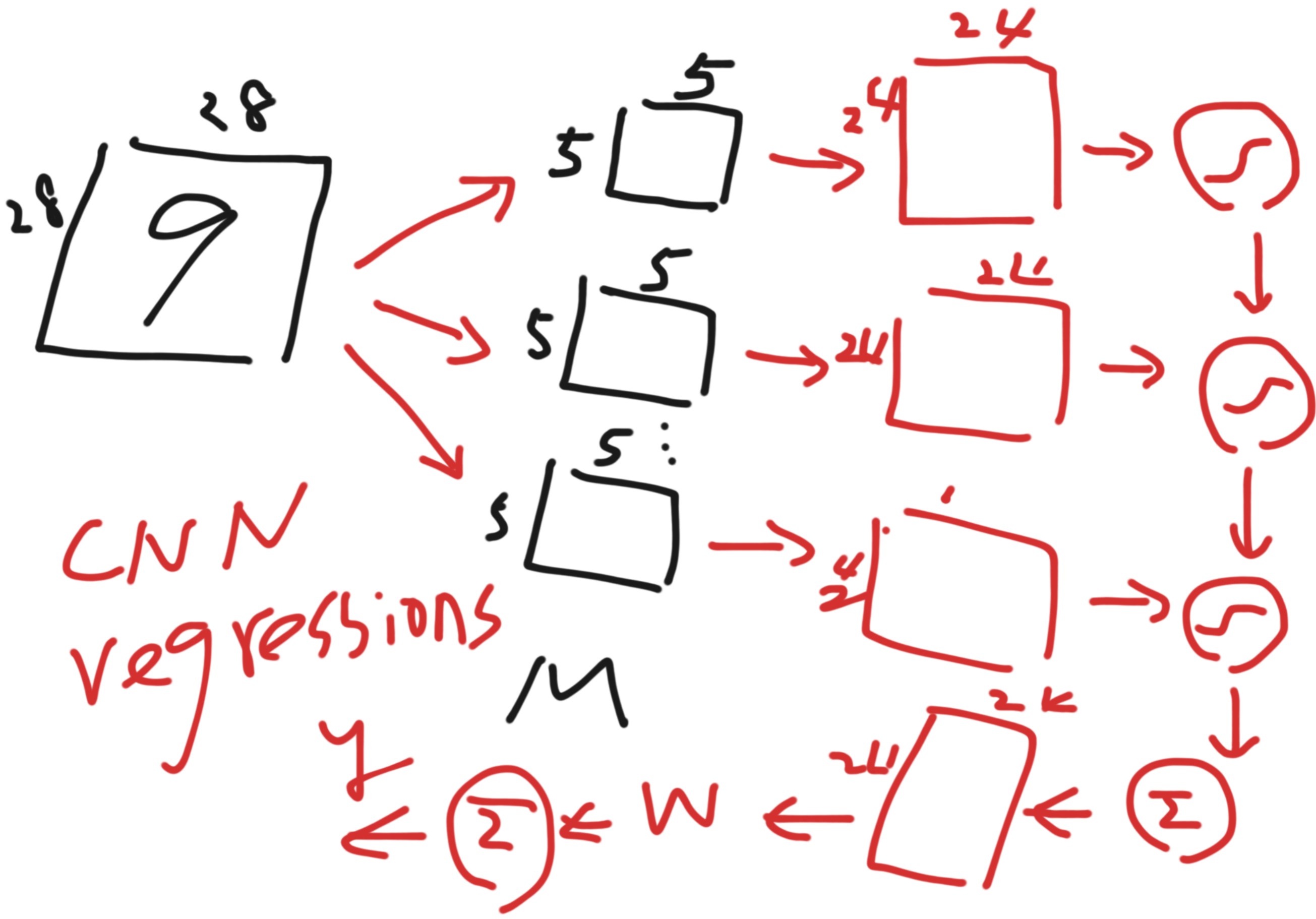


A simple CNN

Levenberg-Marquardt learning
Regressions

Applicability of Levenberg-Marquardt method for learning CNN

- LM method is verified for learning CNN
- A simple CNN is composed of $K=2$ filters in the first hidden layer. The convolution results are transferred by the tanh function and added to form the final output.
- The input is a 3-ary matrix. The matrix size is $28 \times 28 \times 100$. There are 100 28×28 input patterns.



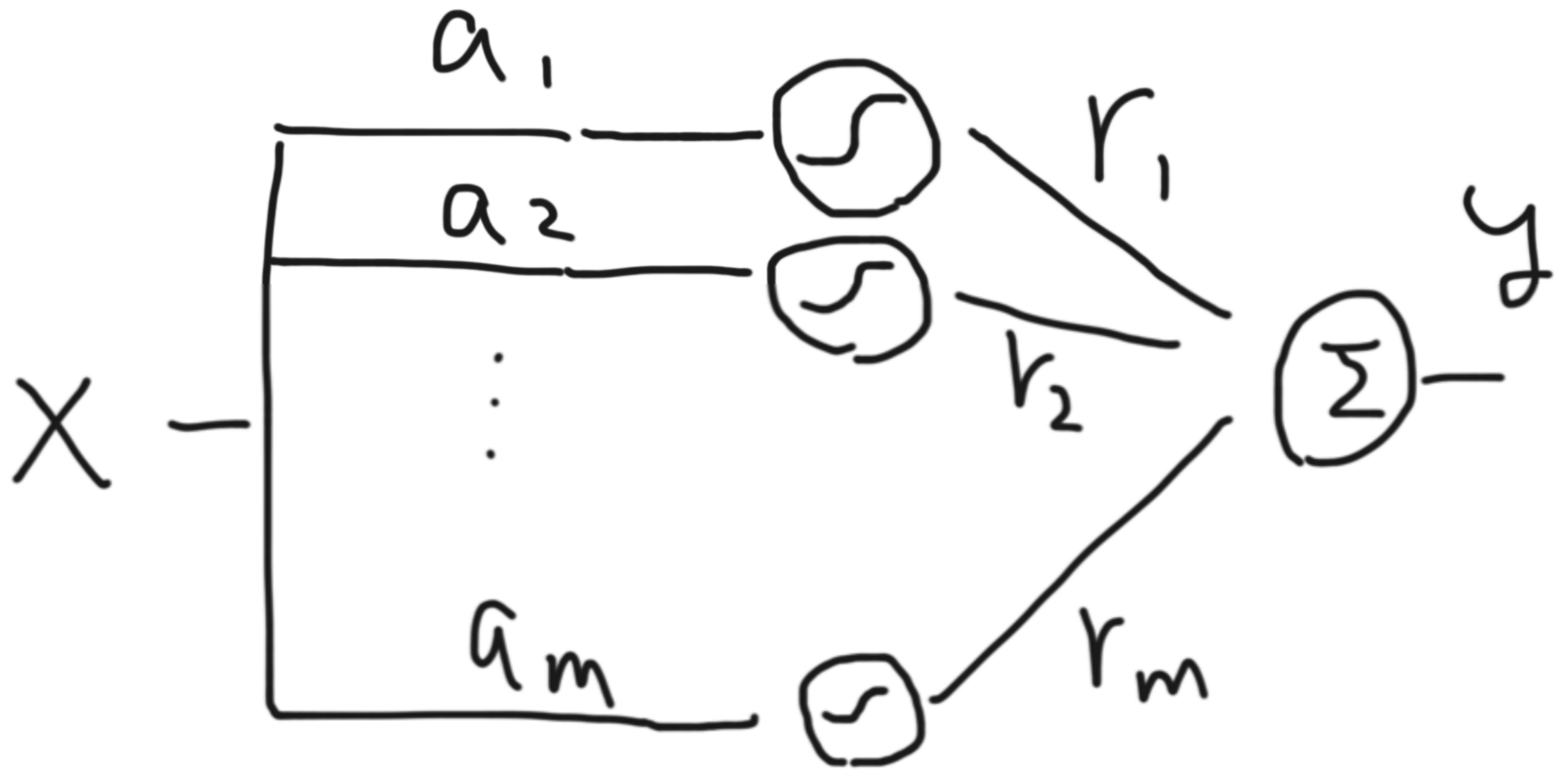
CNN
 regressions



$$f(x; \theta) = \sum_{i=1}^M \gamma_i \tanh(a_i^T x + b_i)$$

adaptive parameters

$$\theta = \{ \gamma_i \in \mathbb{R} \} \cup \{ a_i \in \mathbb{R}^d \} \cup \{ b_i \}$$



multilayer perceptions
MLP

```

function h = g_hat2(x1,x2,c,M)
A = [x1 x2 ones(length(x1),1)];
d=2;W=[];
%W=reshape(c(1:M*(d+1)),d+1,M);
for j=1:M
    W=[W c((j-1)*(d+1)+1:j*(d+1))'];
end
v =tanh(A*W);
h = v*c(M*(d+1)+1:end-1)';
h=h+ones(length(x1),1)*c(end);
end

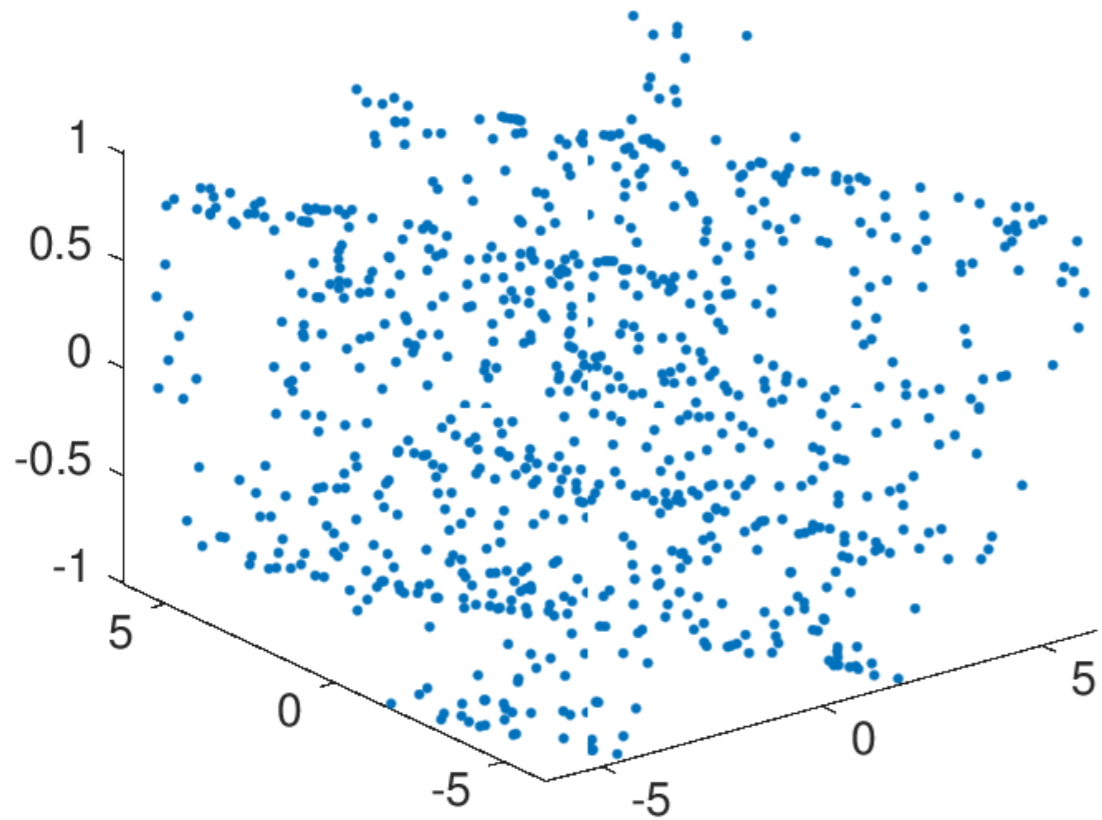
```

$$f(x; \theta) = \sum_{i=1}^M r_i \tanh(a_i^T x + b_i)$$

adaptive parameters
 $\theta = \{r_i \in \mathbb{R}\} \cup \{a_i \in \mathbb{R}^d\} \cup \{b_i\}$

DemoLMlearning

Projection
Tanh

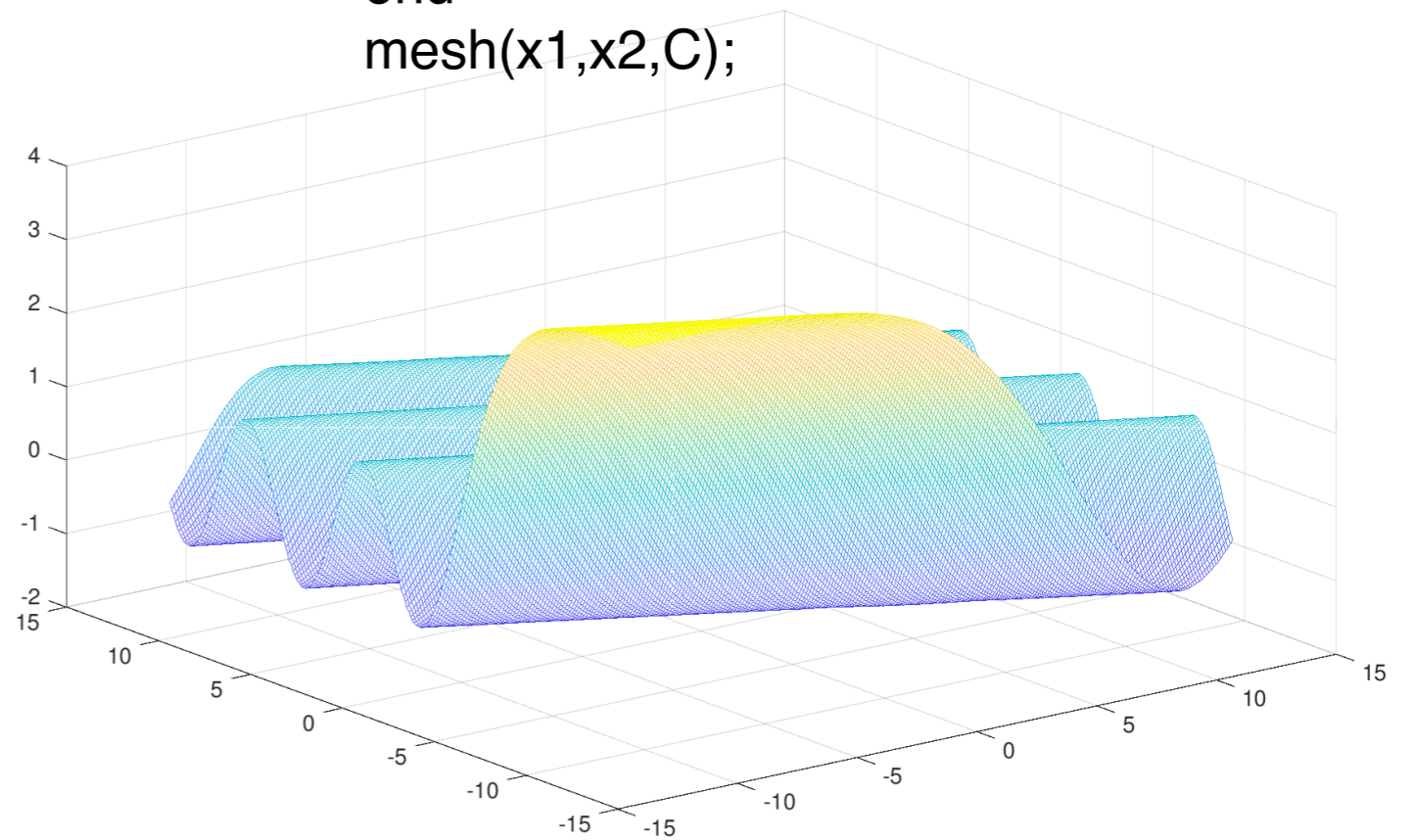


DemoLMlearning

```

range=2*pi
x1=-range:0.1:range;
x2=x1;
for i=1:length(x1)
    C(i,:)=g_hat(x1(i)*ones(length(x2),1),x2',c_z);
end
mesh(x1,x2,C);

```



RBF Network function

$$y(t | \theta) = G(\mathbf{x}[t] | \theta)$$

$$= w_0 + \sum_{m=1}^M w_m \exp\left(-\frac{\|\mathbf{x}[t] - \boldsymbol{\mu}_m\|^2}{2\sigma_m^2}\right)$$

Network parameter

$$\theta = \{w_i\}_i \cup \{\boldsymbol{\mu}_i\}_i \cup \{\sigma_i\}_i$$

$$f(x; \theta) = \sum_{i=1}^M r_i \tanh(a_i^T x + b_i) + r_0$$

adaptive parameters

$$\theta = \{r_i \in \mathbb{R}\} \cup \{a_i \in \mathbb{R}^d\} \cup \{b_i\}$$

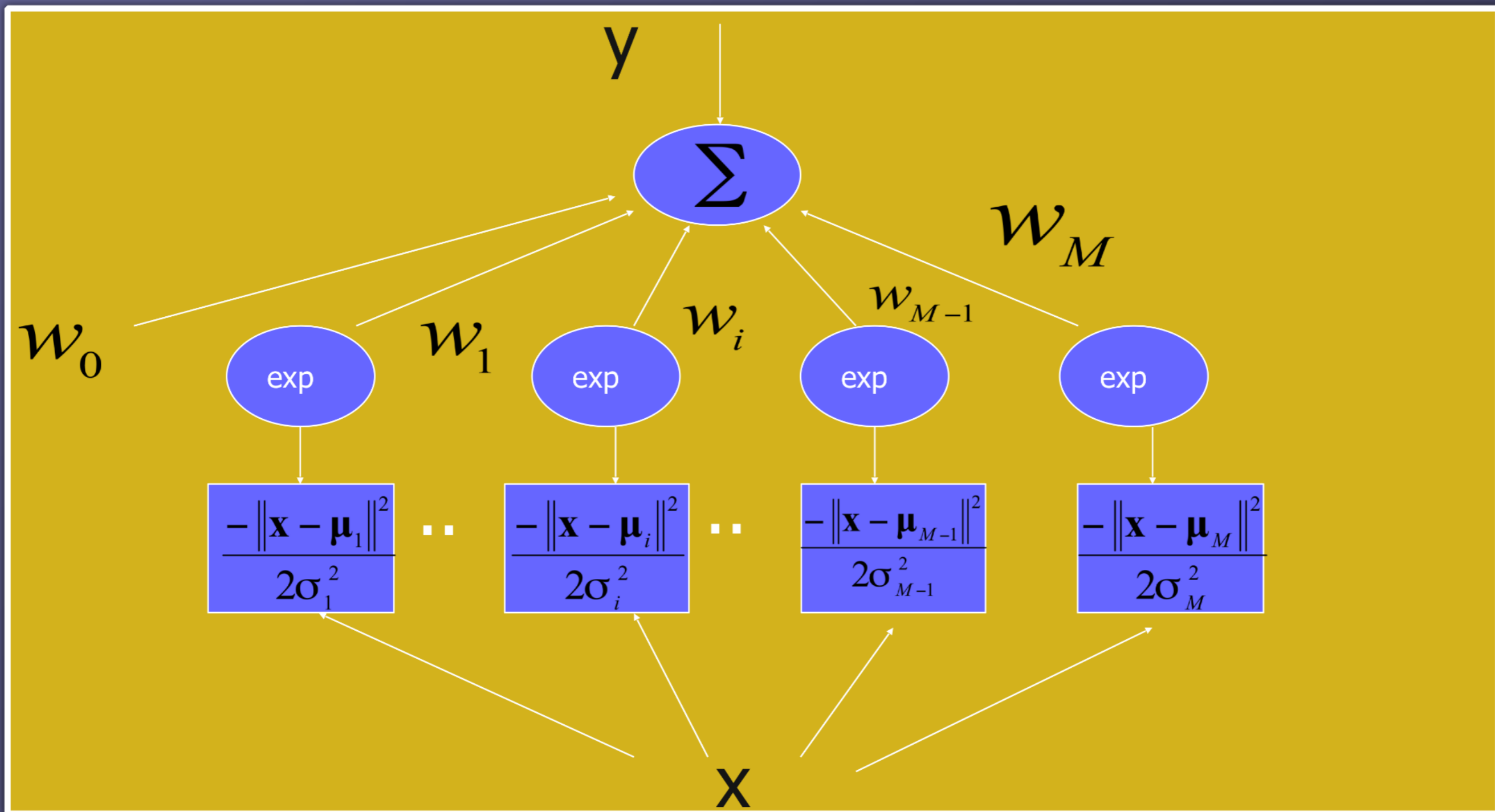
$$y(t | \theta) = G(\mathbf{x}[t] | \theta)$$

$$= w_0 + \sum_{m=1}^M w_m \exp\left(-\frac{\|\mathbf{x}[t] - \boldsymbol{\mu}_m\|^2}{2\sigma_m^2}\right)$$

Network parameter

$$\theta = \{w_i\}_i \cup \{\boldsymbol{\mu}_i\}_i \cup \{\sigma_i\}_i$$

RBF Network



Network parameter

$$\begin{aligned}\theta &= [\mathbf{u}_1^T \mathbf{u}_2^T \cdots \mathbf{u}_M^T \sigma_1 \sigma_2 \cdots \sigma_M \mathbf{w}_0 \mathbf{w}_1 \mathbf{w}_2 \cdots \mathbf{w}_M]^T \\ &= [\theta_1, \dots, \theta_{M*d+2M+1}]\end{aligned}$$

$$w_1 \in \mathcal{M}_{3 \times 1}$$

$$\vdots$$

$$w_M \in \mathcal{M}_{3 \times 1}$$

$$c_1 \in \mathbb{R}$$

$$\vdots$$

$$c_M \in \mathbb{R}$$

$$c_0 \in \mathbb{R}$$

$$\theta = [w_1^T \quad w_2^T \quad \cdots \quad w_M^T \quad c_1 \quad c_2 \quad \cdots \quad c_M \quad c_0]$$

$$\mu_1 \in \mathcal{M}_{2 \times 1}$$

$$\vdots$$

$$\mu_M \in \mathcal{M}_{2 \times 1}$$

$$\delta_1 \in \mathbb{R}$$

$$\vdots$$

$$\delta_M \in \mathbb{R}$$

$$w_1 \in \mathbb{R}$$

$$\vdots$$

$$w_M \in \mathbb{R}$$

$$w_0 \in \mathbb{R}$$

$$\theta = \begin{bmatrix} \mu_1^T & \mu_2^T & \dots & \mu_M^T & \delta_1 & \dots & \delta_M & w_1 & \dots \\ w_M & w_0 \end{bmatrix}$$

```

function h = g_hat2(x1,x2,c,M)
A = [x1 x2 ones(length(x1),1)];
d=2;W=[];
%W=reshape(c(1:M*(d+1)),d+1,M);
for j=1:M
    W=[W c((j-1)*(d+1)+1:j*(d+1))'];
end
% revise
v =tanh(A*W);
h = v*c(M*(d+1)+1:end-1)';
h=h+ones(length(x1),1)*c(end);
end

```

RBF Network function

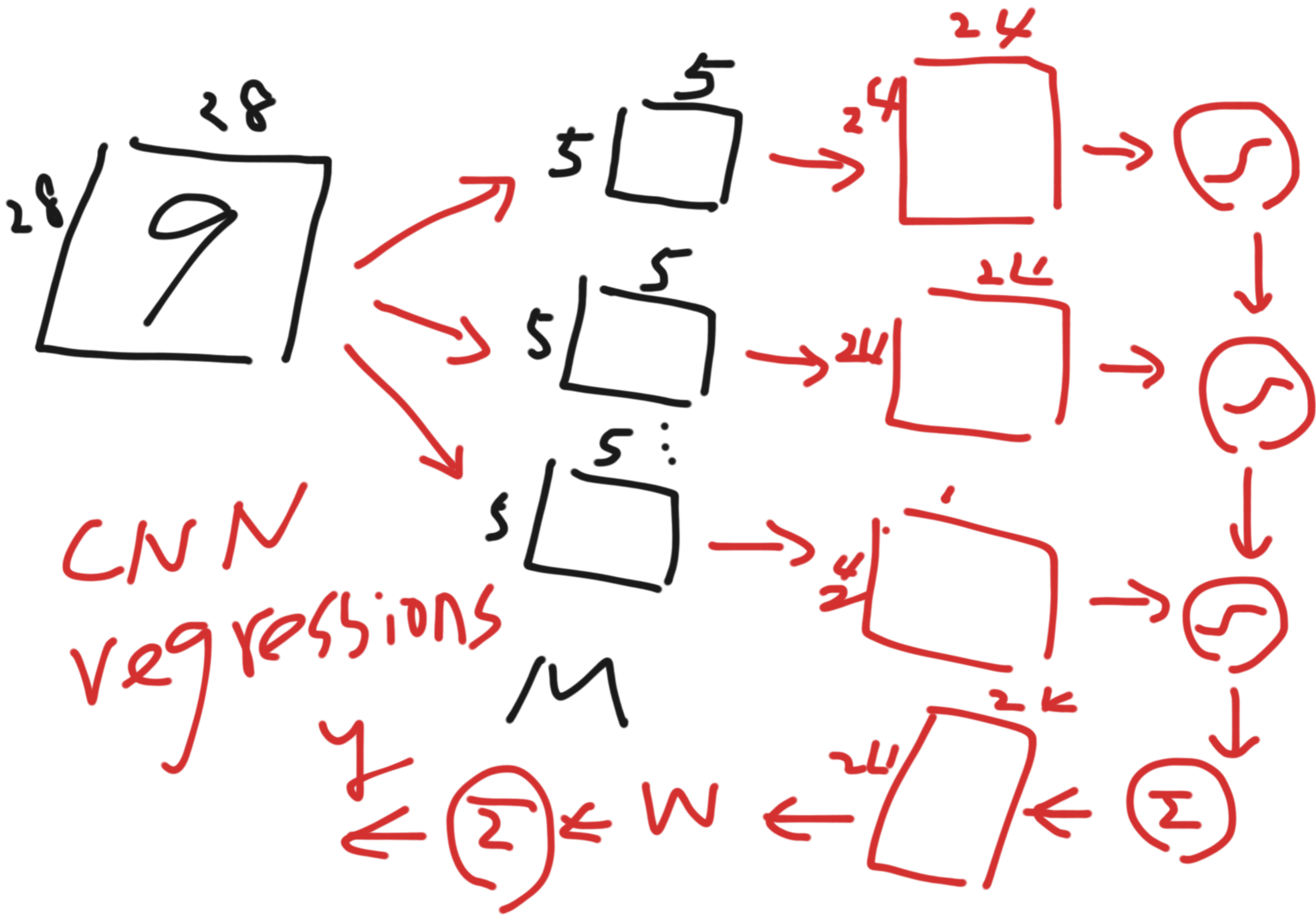
$$y(t | \theta) = G(\mathbf{x}[t] | \theta)$$

$$= w_0 + \sum_{m=1}^M w_m \exp\left(-\frac{\|\mathbf{x}[t] - \boldsymbol{\mu}_m\|^2}{2\sigma_m^2}\right)$$

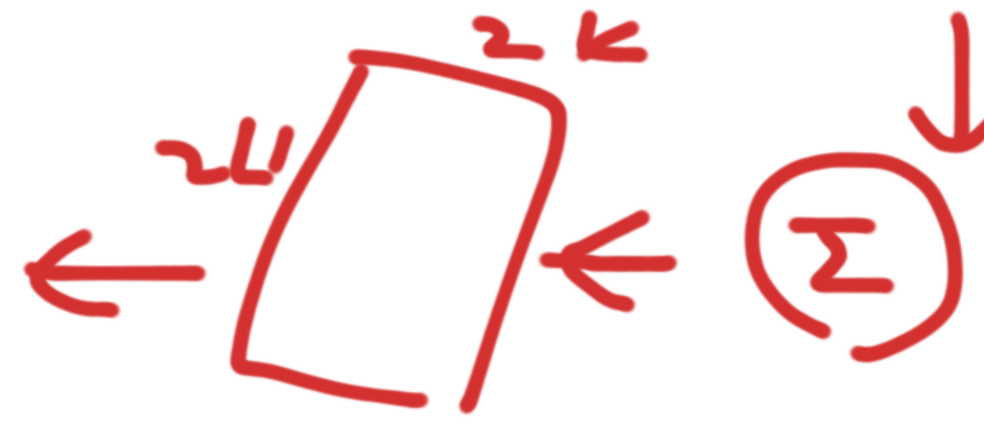
Network parameter

$$\theta = \{w_i\}_i \cup \{\boldsymbol{\mu}_i\}_i \cup \{\sigma_i\}_i$$

DemoLMlear
ning



CNN
 regressions



```

function ans = g_hat_CNN(A,BB,M,f_size)

B_size=M*f_size*f_size;
B=BB(1:B_size);
WW=BB(B_size+1:end);
%
for i=1:M
    cc(i,:) = B((i-1)*f_size^2+1:i*f_size^2);
    for j=1:f_size
        C(j,:,i)=cc(i,(j-1)*f_size+1:j*f_size);
    end
end
W_size=sqrt(length(WW))
for k=1:W_size
    W(k,:)=WW((k-1)*W_size+1:k*W_size)
end
N=size(A,3);
for n=1:N
    v(:,:,n)=zeros(size(A,2)-f_size+1,size(A,2)-f_size+1);
    for i=1:M
        h(:,:,i)=conv(A(:,:,n),C(:,:,i),'valid');
        v(:,:,i)=v(:,:,i)+tanh(h(:,:,i));
    end
    y_hat(:,n)=sum(sum(v(:,:,n).*W));
end

end

```

DemoLMlearning


```

%% Solving a nonlinear system for LM learning, created by Jiann-Ming Wu
% Department of Applied Mathematics, National Dong Hwa University
%
% Using Matlab (R)
% 2018 dec. 25
% learning is resolved by the Levenberg-Marquardt method
%

```

```

function demo_LM_CNN_regressions()
syms c % adaptable parameters in an MLP network
M=3;d=28;N=300
f_size=5;
% initialization
c0_size=f_size*f_size*M;
c0_size=c0_size+(d-f_size+1)^2
c0=rand(1,c0_size)*2-1;
size(c0)
% preparation of training data
% uniform sampling
% Substitute to the target function g
z=rand(d,d,N);
A=z>0.5;
y=rand(N,1)*0.3-0.15;
size(y)

y_hat = g_hat_CNN(z,c0,M,f_size);

size(y_hat)
% Levenberg-Marquardt method
options = optimoptions('fsolve','Algorithm','levenberg-marquardt')
% specification of a nonlinear system for MLP_learning
f = @(c)learning_CNN(c,A,y,M,f_size);

% apply fsolve
% Verification of c_zero
c_zero = fsolve(f,c0,options);
BB=c_zero;
F = learning_CNN(BB,A,y,M,f_size);
mean((F).^2)
%mean((g_hat2(z(:,1),z(:,2),c_zero,M)-y).^2)
% testing phase
%z_test=rand(100,2)*2*pi-pi;
%y_test=g_sin(z_test(:,1),z_test(:,2));
%mean((g_hat2(z_test(:,1),z_test(:,2),c_zero,M)-y_test).^2)
end

```

```

function F = learning_CNN(BB,A,y,M,f_size)
B_size=M*f_size*f_size;
B=BB(1:B_size);
WW=BB(B_size+1:end);
%
for i=1:M
    cc(i,:) = B((i-1)*f_size^2+1:i*f_size^2);
    for j=1:f_size
        C(j,:,i)=cc(i,(j-1)*f_size+1:j*f_size);
    end
end
W_size=sqrt(length(WW))
for k=1:W_size
    W(k,:)=WW((k-1)*W_size+1:k*W_size);
end
N=size(A,3);
for n=1:N
    v(:,:,n)=zeros(size(A,2)-f_size+1,size(A,2)-f_size+1);
    for i=1:M
        h(:,:,i)=convn(A(:,:,n),C(:,:,i),'valid');
        v(:,:,n)=v(:,:,n)+tanh(h(:,:,i));
    end
    y_hat(n)=sum(sum(v(:,:,n).*W));
end
F=y_hat;
F =F-y;
end
function y_hat = g_hat_CNN(A,BB,M,f_size)

B_size=M*f_size*f_size;
B=BB(1:B_size);
WW=BB(B_size+1:end);
%
for i=1:M
    cc(i,:) = B((i-1)*f_size^2+1:i*f_size^2);
    for j=1:f_size
        C(j,:,i)=cc(i,(j-1)*f_size+1:j*f_size);
    end
end
W_size=sqrt(length(WW))
for k=1:W_size
    W(k,:)=WW((k-1)*W_size+1:k*W_size);
end
N=size(A,3);
for n=1:N
    v(:,:,n)=zeros(size(A,2)-f_size+1,size(A,2)-f_size+1);
    for i=1:M
        h(:,:,i)=convn(A(:,:,n),C(:,:,i),'valid');
        v(:,:,n)=v(:,:,n)+tanh(h(:,:,i));
    end
    y_hat(n)=sum(sum(v(:,:,n).*W));
end
end

```