

Lecture 5II

- Nonlinear equations
- Nested FOR loops
- Vector codes

Nonlinear system f1

$$x_1^2 + x_2^2 - 4 = 0$$

$$x_1 - x_2 = 0$$

Nonlinear system f2

SOLVE

$$f_1(x_1, x_2) = 2x_1^2 + x_2^2 - 24 = 0$$

$$f_2(x_1, x_2) = x_1^2 - x_2^2 + 12 = 0$$

Nonlinear system f3

$$f_1(x) = \exp(x_1) + x_2 * x_3 - 3 = 0$$

$$f_2(x) = \frac{x_1}{x_2} + x_3^2 - \log(x_2) = 0$$

$$f_3(x) = \frac{x_1}{x_1 + x_2 + x_3} - \sin(x_3) = 0$$

nonlinear functions

$$F(x_1, x_2) = \begin{bmatrix} f_1(x_1, x_2) \\ f_2(x_1, x_2) \end{bmatrix}$$

$$f_1(x_1, x_2) = x_1^2 + x_2^2 - 4$$

$$f_2(x_1, x_2) = x_1 - x_2$$

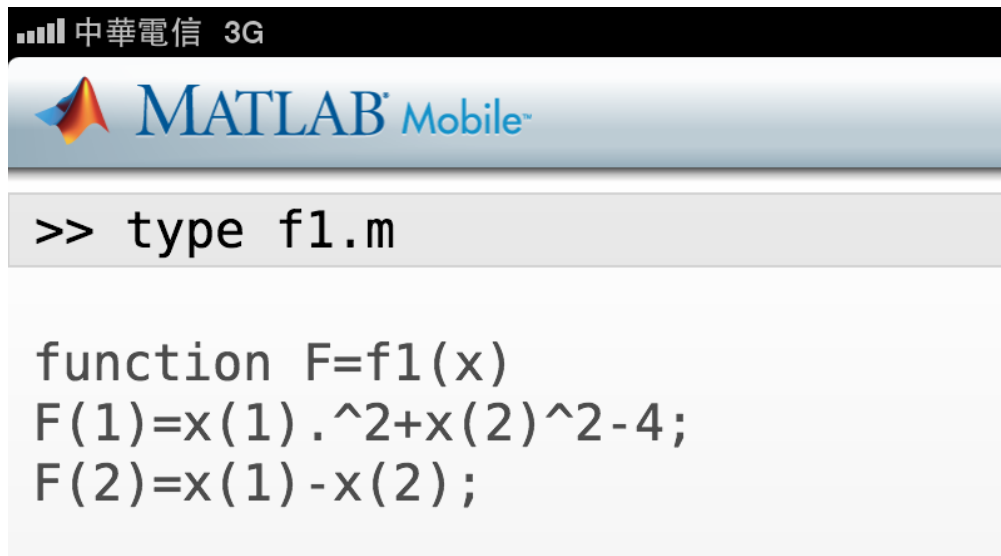
Function evaluation

```
function F = f1(x)
```

```
    F(1) = x(1).^2 + x(2)^2 - 4;
```

```
    F(2) = x(1) - x(2);
```

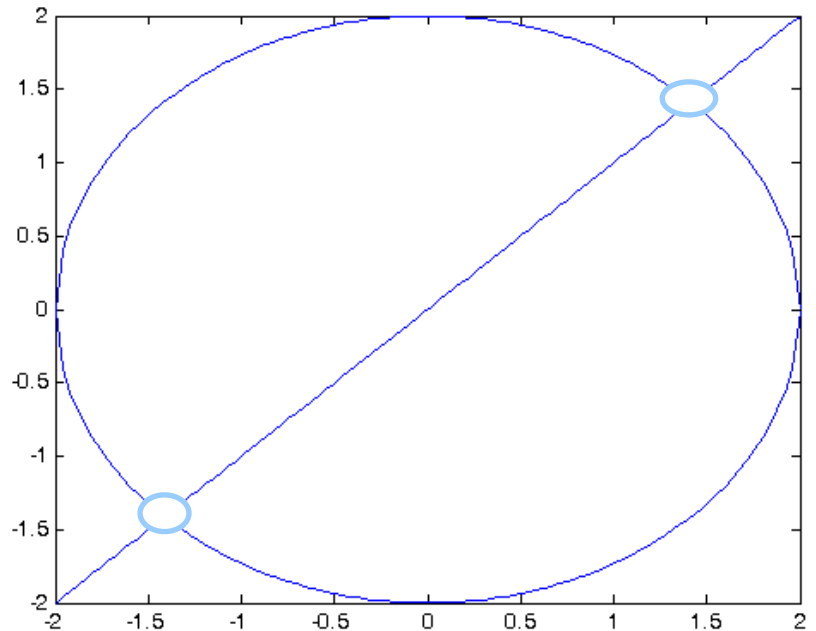
```
return
```



```
中华電信 3G  
MATLAB Mobile  
>> type f1.m  
  
function F=f1(x)  
F(1)=x(1).^2+x(2)^2-4;  
F(2)=x(1)-x(2);
```

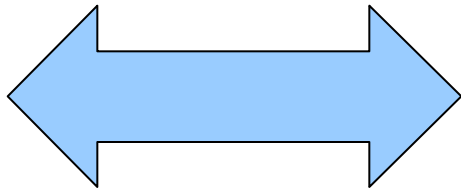
Geometric interpretation

```
x=linspace(-2,2);  
plot(x,x); hold on;  
plot(x,sqrt(4-x.^2))  
plot(x,-sqrt(4-x.^2))
```



Least square of nonlinear functions

$$\min_{x_1, x_2} \sum_i f_i(x_1, x_2)^2$$



SOLVE

$$f_1(x_1, x_2) = x_1^2 + x_2^2 - 4 = 0$$

$$f_2(x_1, x_2) = x_1 - x_2 = 0$$

Find a zero

```
x0= ones(1,2)*2;  
x = lsqnonlin(@f1,x0)
```

```
y=f1(x);  
sum(y.^2)
```

CHECKING

Multiple roots

```
v=[]
```

```
for i=1:n
```

```
x0= rand(1,2)*2;  
x = lsqnonlin(@f1,x0)  
v=[v;x];  
plot(x(1),x(2),'o');
```

Multiple roots

```
v=[]
```

```
for i=1:n
```

```
x0= rand(1,2)*2;  
x = fsolve(@f1,x0)  
v=[v;x];  
plot(x(1),x(2),'o');
```

Function evaluation

```
function F = f2(x)
    F(1) = 2*x(1).^2 + x(2)^2-24;
    F(2) = x(1).^2 - x(2).^2+12;
return
```

$$f_1(x_1, x_2) = 2x_1^2 + x_2^2 - 24 = 0$$

$$f_2(x_1, x_2) = x_1^2 - x_2^2 + 12 = 0$$

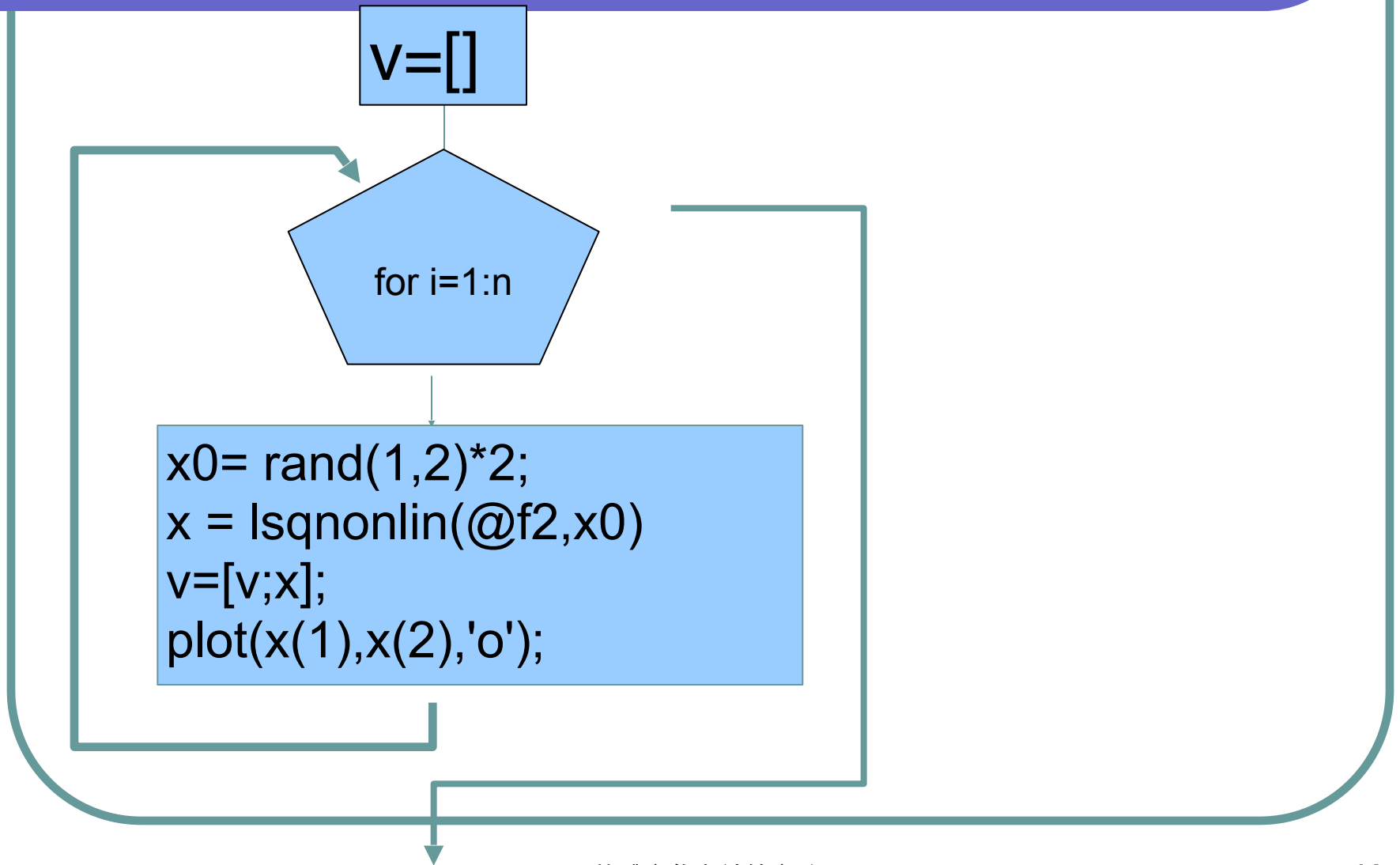
Find a zero

```
x0= ones(1,2)*2;  
x = lsqnonlin(@f2,x0)
```

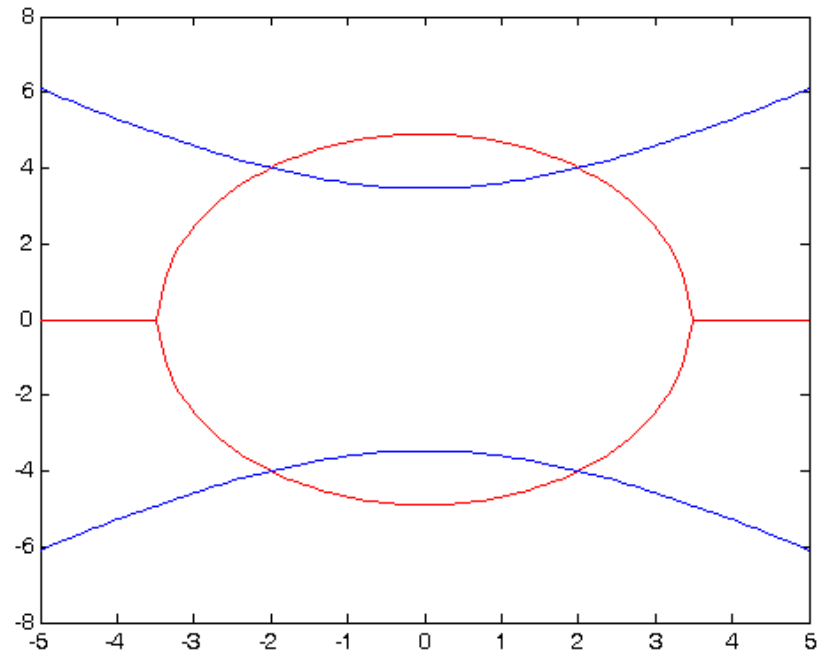
```
y=f2(x);  
sum(y.^2)
```

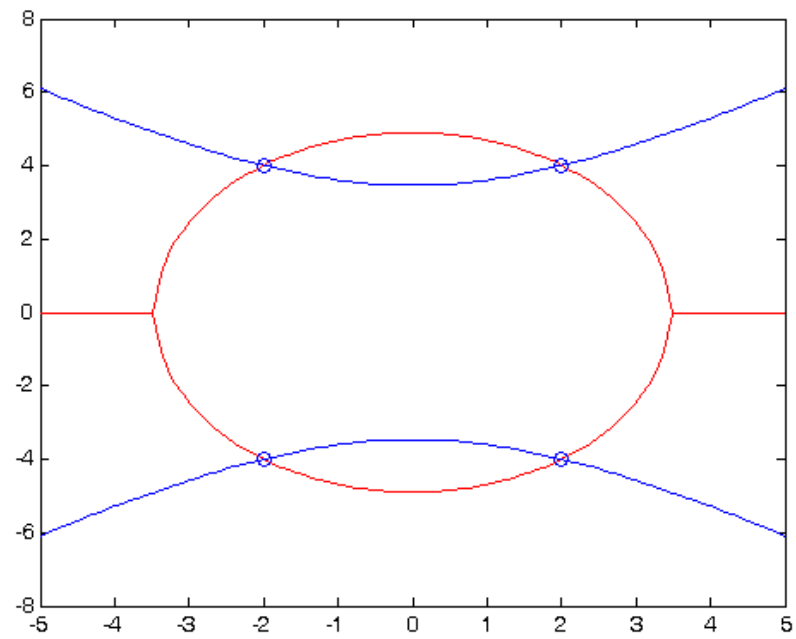
CHECKING

Multiple roots



```
x=linspace(-5,5);  
plot(x,sqrt(24-2*x.^2),'r');hold on;  
plot(x,-sqrt(24-2*x.^2),'r')  
plot(x,sqrt(12+x.^2),'b')  
plot(x,-sqrt(12+x.^2),'b')
```





SOLVE

$$f_1(x_1, x_2) = x_1^2 - 2x_2^2 - 2 = 0$$

$$f_2(x_1, x_2) = x_1x_2 - 2 = 0$$

Function evaluation

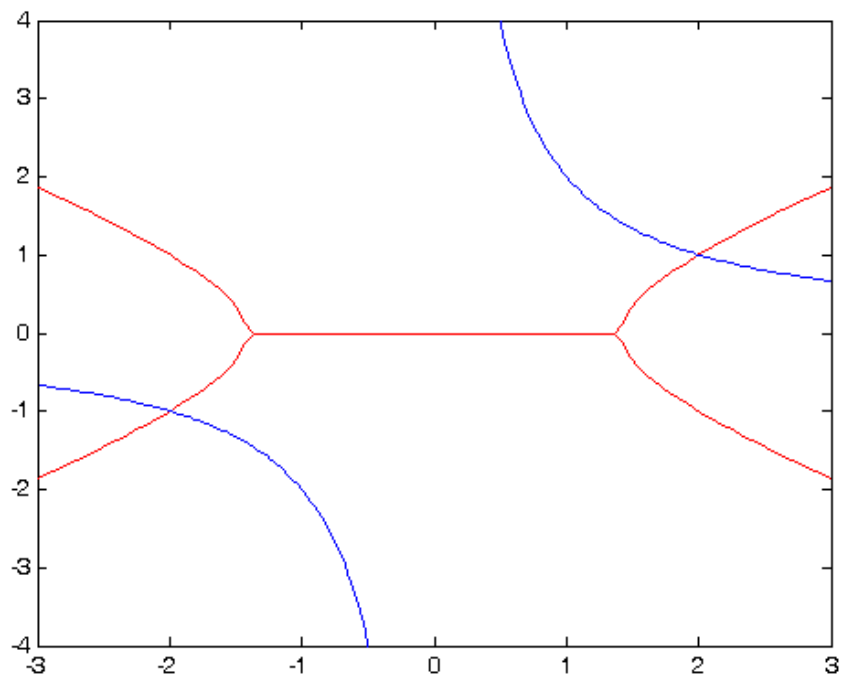
```
function F = myfun3(x)
    F(1) = x(1).^2 - 2*x(2)^2 - 2;
    F(2) = x(1).*x(2) - 2;
return
```

SOLVE

$$f_1(x_1, x_2) = x_1^2 - 2x_2^2 - 2 = 0$$

$$f_2(x_1, x_2) = x_1x_2 - 2 = 0$$

```
x=linspace(-3,3);  
x=x(find(abs(x) > 0.1));  
plot(x,sqrt((x.^2-2)/2),'r');hold on;  
plot(x,-sqrt((x.^2-2)/2),'r')  
x=linspace(0.5,3);  
plot(x,2./x,'b');  
x=linspace(-0.5,-3);  
plot(x,2./x,'b')
```



Find a zero

```
x0= ones(1,2)*2;  
x = lsqnonlin(@myfun3,x0)
```

```
y=myfun3(x);  
sum(y.^2)
```

CHECKING

Multiple roots

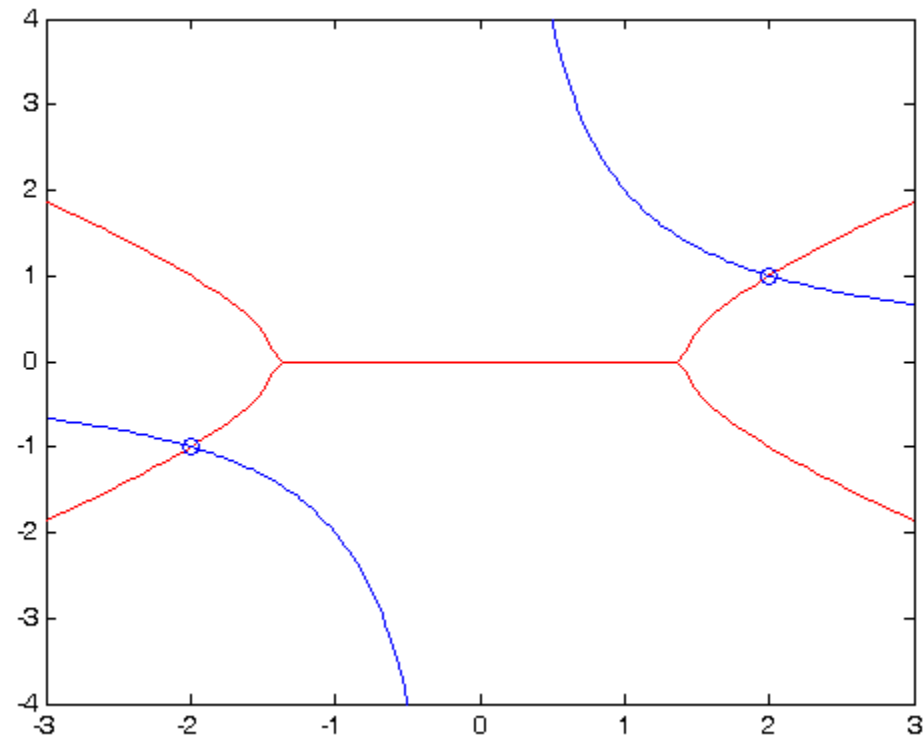
```
v=[]
```

```
for i=1:n
```

```
x0=rand(1,2)*2;  
x = lsqnonlin(@myfun3,x0)  
v=[v;x];  
plot(x(1),x(2),'o');
```

demo_lsq_hyperbola.m

two_hyperbola.m



Nonlinear system f3

$$f_1(x) = \exp(x_1) + x_2 * x_3 - 3 = 0$$

$$f_2(x) = \frac{x_1}{x_2} + x_3^2 - \log(x_2) = 0$$

$$f_3(x) = \frac{x_1}{x_1 + x_2 + x_3} - \sin(x_3) = 0$$

```
function F=f3(x)
F(1)=exp(x(1))+x(2)*x(3)-3;
F(2)=x(1)/x(2)+x(3).^2-log(x(2));
F(3)=x(1)/(x(1)+x(2)+x(3))-sin(x(3));
```

Matrix Multiplication

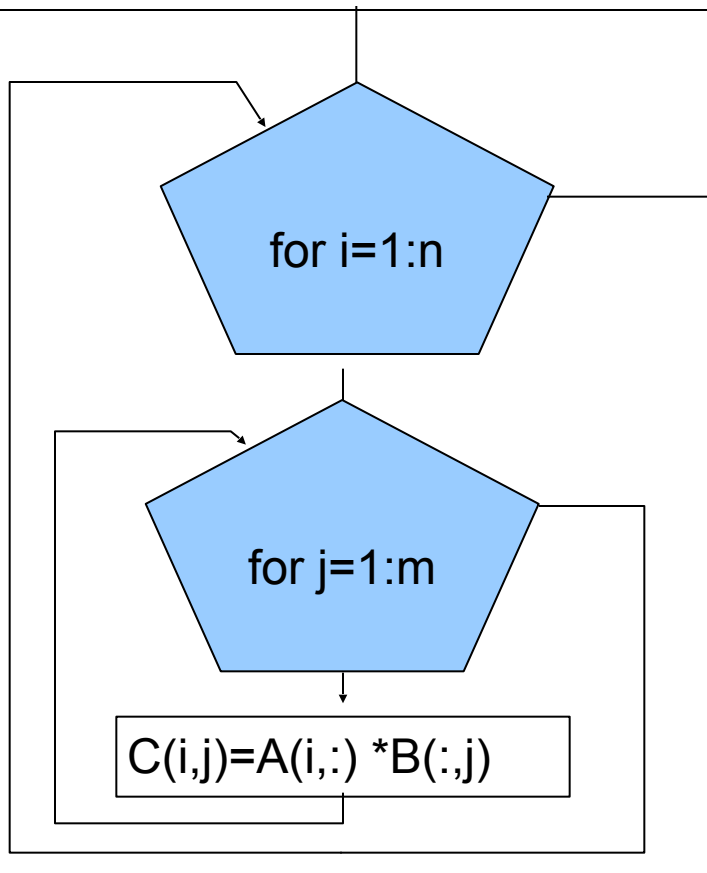
- $C=A*B$
- $C(i,j)=A(i,:) * B(:,j)$ for all i,j

$$C = A B$$

$$\begin{bmatrix} 1 & 2 & 1 \\ 2 & 4 & 4 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & 2 & 1 \\ 1 & 2 & 2 \end{bmatrix}$$

Nested for-loops

```
[n,d1]=size(A);[d2,m]=size(B)
```



$$C = A B$$
$$\begin{bmatrix} 1 & 2 & 1 \\ 2 & 4 & 4 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & 2 & 1 \\ 1 & 2 & 2 \end{bmatrix}$$

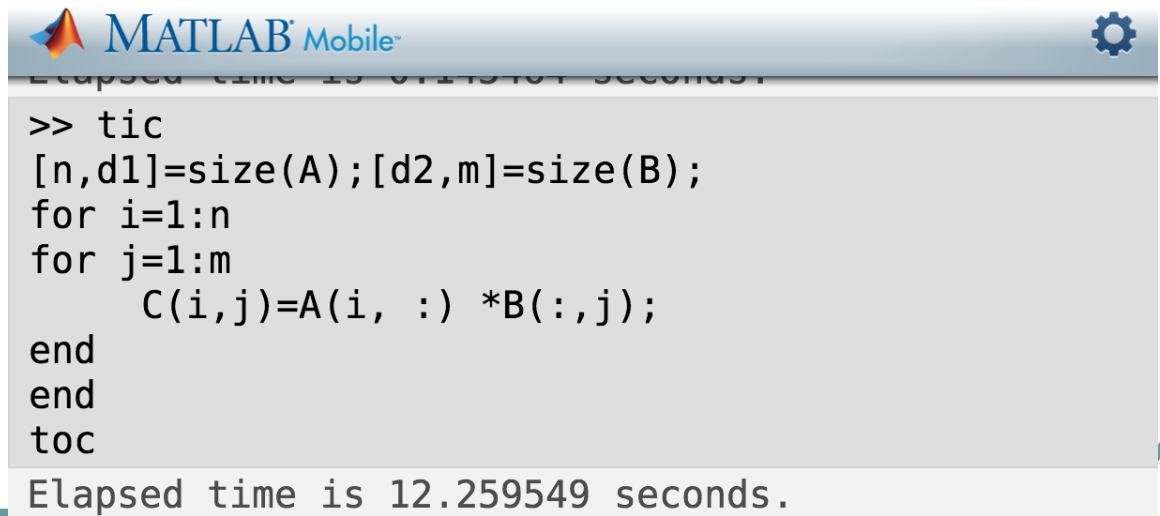
```
[n,d1]=size(A);[d2,m]=size(B);  
for i=1:n  
for j=1:m  
    C(i,j)=A(i, :) *B(:,j);  
end  
end
```

CPU time

```
A=rand(2000,100);B=rand(100,2000);  
[n,d1]=size(A);[d2,m]=size(B);  
tic  
C=A*B;  
toc
```

```
>> A=rand(2000,100);B=rand(100,2000);  
[n,d1]=size(A);[d2,m]=size(B);  
tic  
C=A*B;  
toc
```

```
tic
[n,d1]=size(A);[d2,m]=size(B);
for i=1:n
for j=1:m
    C(i,j)=A(i, :) *B(:,j);
end
end
toc
```



The image shows a screenshot of the MATLAB Mobile application. At the top, there is a header with the MATLAB logo and the text "MATLAB Mobile" on the left, and a gear icon on the right. Below the header, there is a code editor area containing the same MATLAB code as in the previous block. Below the code editor, there is a command window area showing the output of the code execution: "Elapsed time is 12.259549 seconds."

```
>> tic
[n,d1]=size(A);[d2,m]=size(B);
for i=1:n
for j=1:m
    C(i,j)=A(i, :) *B(:,j);
end
end
toc
```

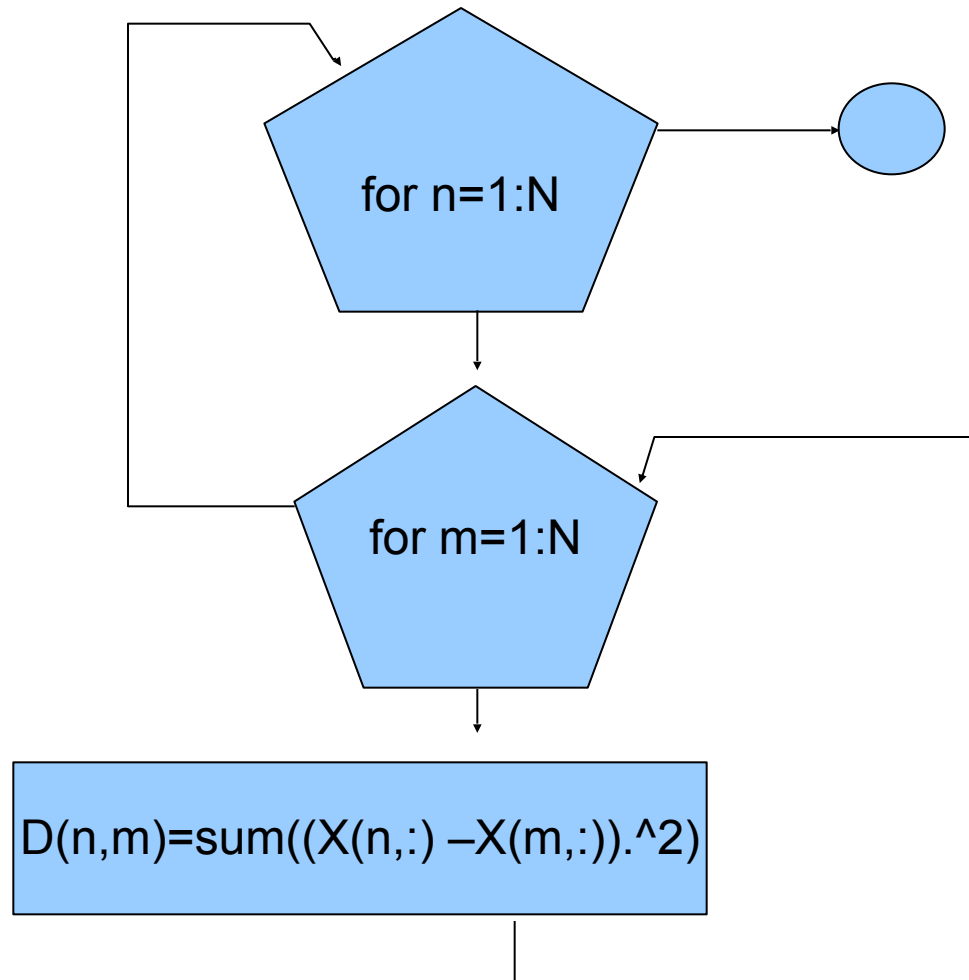
Elapsed time is 12.259549 seconds.

Calculation of Cross distances

- Given N points X : $N \times 200$
- D : $N \times N$
- $D(i,j)$ denotes the distance between $X(i,:)$ and $X(j,:)$
- Given X , find D

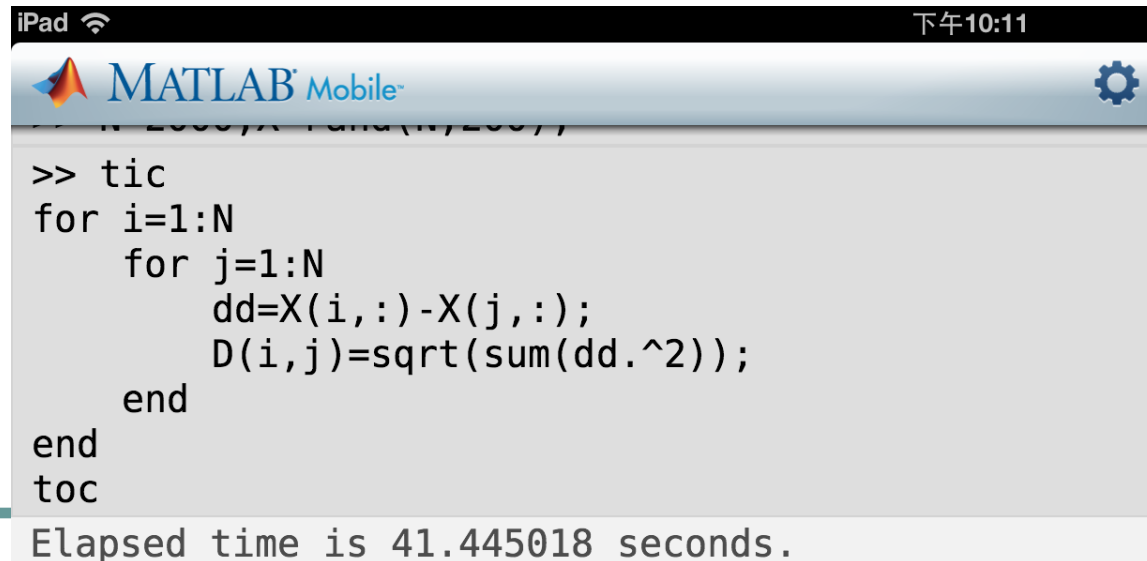
```
>> N=2000;X=rand(N,200);
```

Nested loops for cross distances



Matlab codes for nested codes

```
tic
• for i=1:N
    for j=1:N
        dd=X(i,:)-X(j,:);
        D(i,j)=sqrt(sum(dd.^2));
    end
end
end
toc
```



The screenshot shows the MATLAB Mobile interface on an iPad. The top status bar displays 'iPad' and the time '下午10:11'. The app title is 'MATLAB Mobile'. The command window contains the following code:

```
>> tic
for i=1:N
    for j=1:N
        dd=X(i,:)-X(j,:);
        D(i,j)=sqrt(sum(dd.^2));
    end
end
toc
```

Below the code, the output indicates the execution time: 'Elapsed time is 41.445018 seconds.'

- Straightforward implementation
- Nested for-looping
 - A loop within a loop
 - $N \times N$ calculations of distances
- Time consuming for large N and d

Vector codes

- How to calculate cross distances without using for-looping or while-looping ?
- Vector codes are loop-free
- Vector codes for cross distances can significantly improve efficiency against nested looping in computation

$$\begin{aligned} D_{ij} &= (x_i - x_j)(x_i^T - x_j^T) \\ &= x_i x_i^T - 2x_i x_j^T + x_j x_j^T \\ &= A_{ij} - 2B_{ij} + C_{ij} \end{aligned}$$

D : cross distances between N points

Matrix D is decomposed to matrices A, B and C

A : elements in each row are identical

B : multiplication of matrix X and transpose of matrix X

C : elements in each column are identical


$$\begin{aligned}
 D_{ij} &= (x_i - x_j)(x_i^T - x_j^T) \\
 &= x_i x_i^T - 2x_i x_j^T + x_j x_j^T \\
 &= A_{ij} - 2B_{ij} + C_{ij}
 \end{aligned}$$

```

tic
N=size(X,1);
A=sum(X.^2,2)*ones(1,N);
C=ones(N,1)*sum(X.^2,2)';
B=X*X';
D=sqrt(A-2*B+C);
toc

```

iPad

 MATLAB Mobile

Elapsed time is 41.445018 seconds.

```

>> tic
N=size(X,1);
A=sum(X.^2,2)*ones(1,N);
C=ones(N,1)*sum(X.^2,2)';
B=X*X';
D=sqrt(A-2*B+C);
toc

```

Elapsed time is 1.712473 seconds.

Check equivalence

- ```
>> DD=sqrt(A-2*B+C);
```

```
>> sum(sum(abs(D-DD)))
```

```
ans =
```

```
0
```

# Cross distances between matrices X and Y

demo\_distance2.m

```
7 - for i=1:N
8 - for j=1:M
9 - dd=X(i,:)-Y(j,:);
10 - D(i,j)=sqrt(sum(dd.^2));
11 - end
12 - end
13 - ss2=cputime;
14 - A=sum(X.^2,2)*ones(1,M);
15 - C=ones(N,1)*sum(Y.^2,2)';
16 - B=X*Y';
17 - DD=sqrt(A-2*B+C);
18 - sum(sum(abs(DD-D)))
```

# Constrained optimization

$$-2 \leq x_1 \leq 10$$

$$0 \leq x_2 \leq 10$$

Inequality constraint

$$x_2 \leq x_1$$

Nonlinear equality

$$x_1^2 + x_2^2 = 13$$

# Constrained optimization

$$\min_{x_1, x_2} (x_1^2 + x_2^2 - 13)^2$$

$$-2 \leq x_1 \leq 10$$

$$0 \leq x_2 \leq 10$$

$$x_2 \leq x_1$$

# Constraints

- Lower bound and upper bound
- Equality constraint
- Inequality constraint



# Constraints

Lower bound  $[-2, 0] \leq [x_1, x_2]$

Upper bound  $[x_1, x_2] \leq [10, 10]$

Inequality constraints

$$x_2 \leq x_1$$

$$\begin{bmatrix} -1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \leq 0$$

# Demo\_conop2

## demo\_conop2.m

```
function demo_conop2()
lb =[-2 0];
ub =[10,10];
Aeq=[-1 1];beq=[0];
A=[];b=[];
x = fmincon(@fun,[1 1],A,b,Aeq,beq,lb,ub)
x(1).^2+x(2).^2
return
function y = fun(x)
y = (x(1).^2+x(2).^2-13).^2;
return
```

# Objective function

```
function y = fun(x)
y = (x(1).^2+x(2).^2-13).^2;
return
```

# Calling fmincon

```
x = fmincon(@fun,[1 1],A,b,Aeq,beq,lb,ub)
```

objective  
function

initial  
guess

linear  
equality

inequality

Lower and upper  
bound

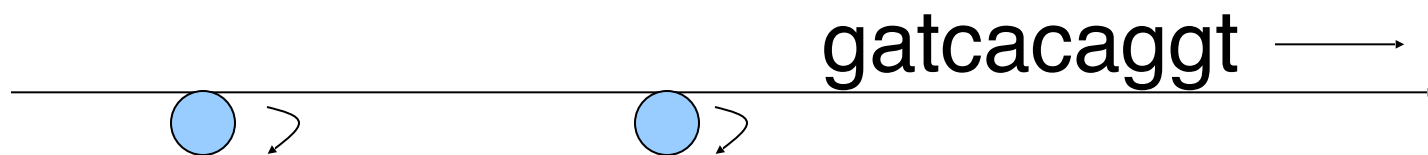
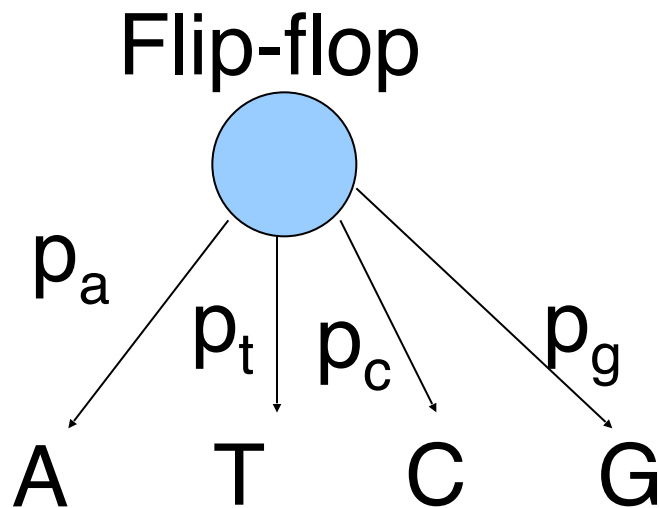
# Random variable

- Sample space  $S=\{A, T, C, G\}$
- $X$  is a discrete random variable with sample space  $S$ .

$$\begin{aligned}\Pr(X = A) &= p_a & \Pr(X = T) &= p_t \\ \Pr(X = C) &= p_c & \Pr(X = G) &= p_g\end{aligned}$$

# Generative model

$$p_a + p_t + p_c + p_g = 1$$

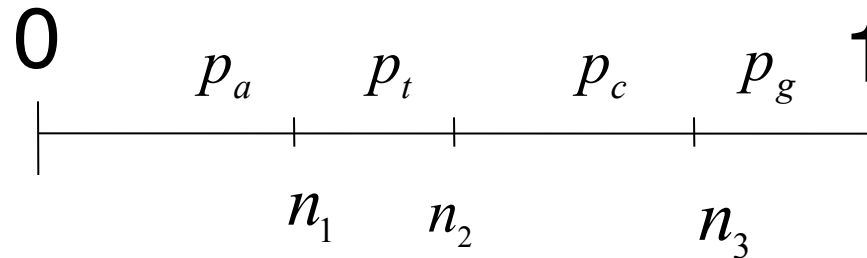


# Partition

$$n_1 = p_a$$

$$n_2 = p_a + p_t$$

$$n_3 = p_a + p_t + p_c$$



Knots  $n_1, n_2$  and  $n_3$  partition  $[0, 1]$  into four intervals respectively with lengths,  $p_a, p_t, p_c$  and  $p_g$

```
r=rand;
Tag= (r<=c(1))+ 2*(r<=c(2) & r > c(1))+3*(r<=c(3) & r > c(2))+4*(r<=c(4) & r > c(3))
switch Tag
case 1
 s=[s 'A'];
case 2
 s=[s 'T'];
case 3
 s=[s 'C'];
case 4
 s=[s 'G'];
end
```



# Sequence generation

- Emulation of a generative model for creation of an atcg sequence

# FOR Loops

```
input p,m
n=length(p)
p_sum=0;s=[];
```

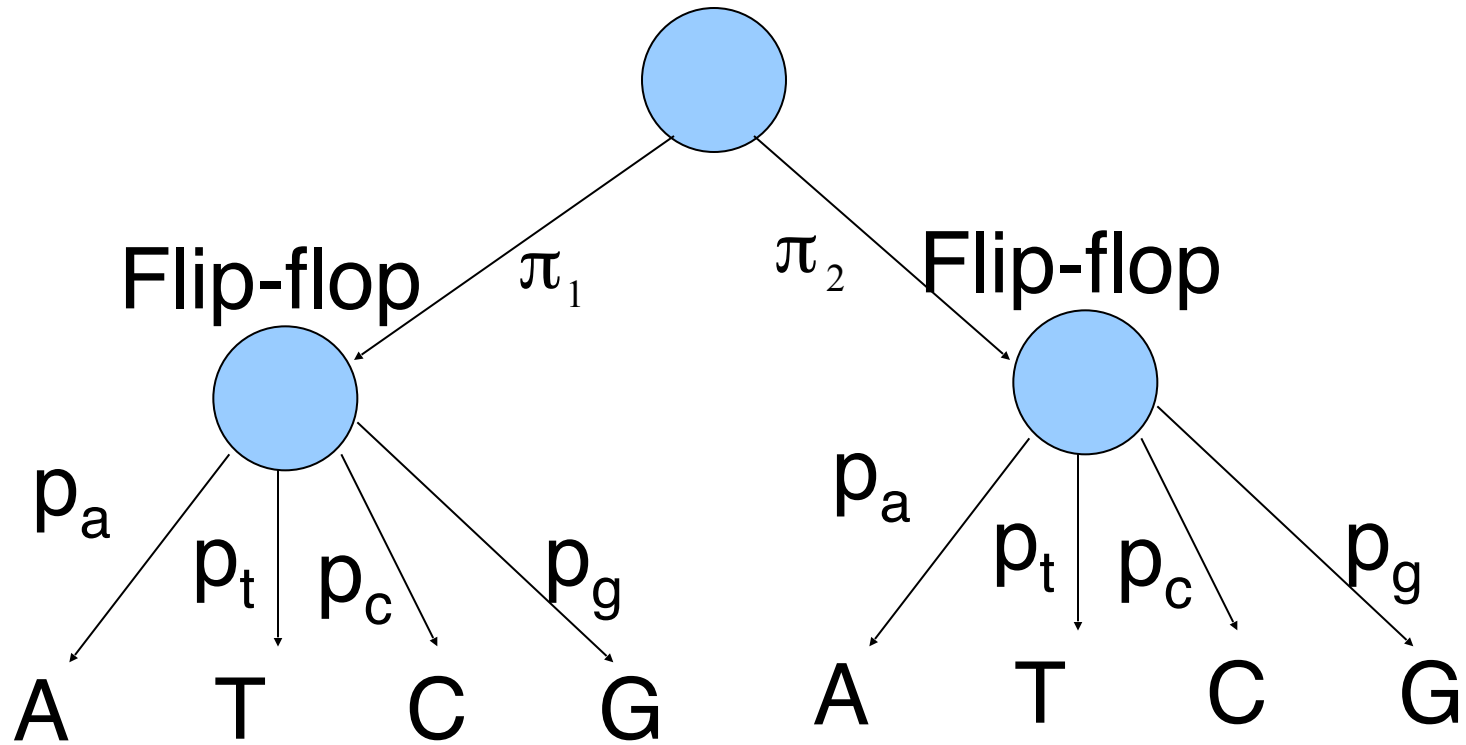
```
for i=1:n
```

```
p_sum=p_sum+p(i);
c(i)=p_sum;
```

```
for j=1:m
```

```
r=rand;
switch r
...
end
```

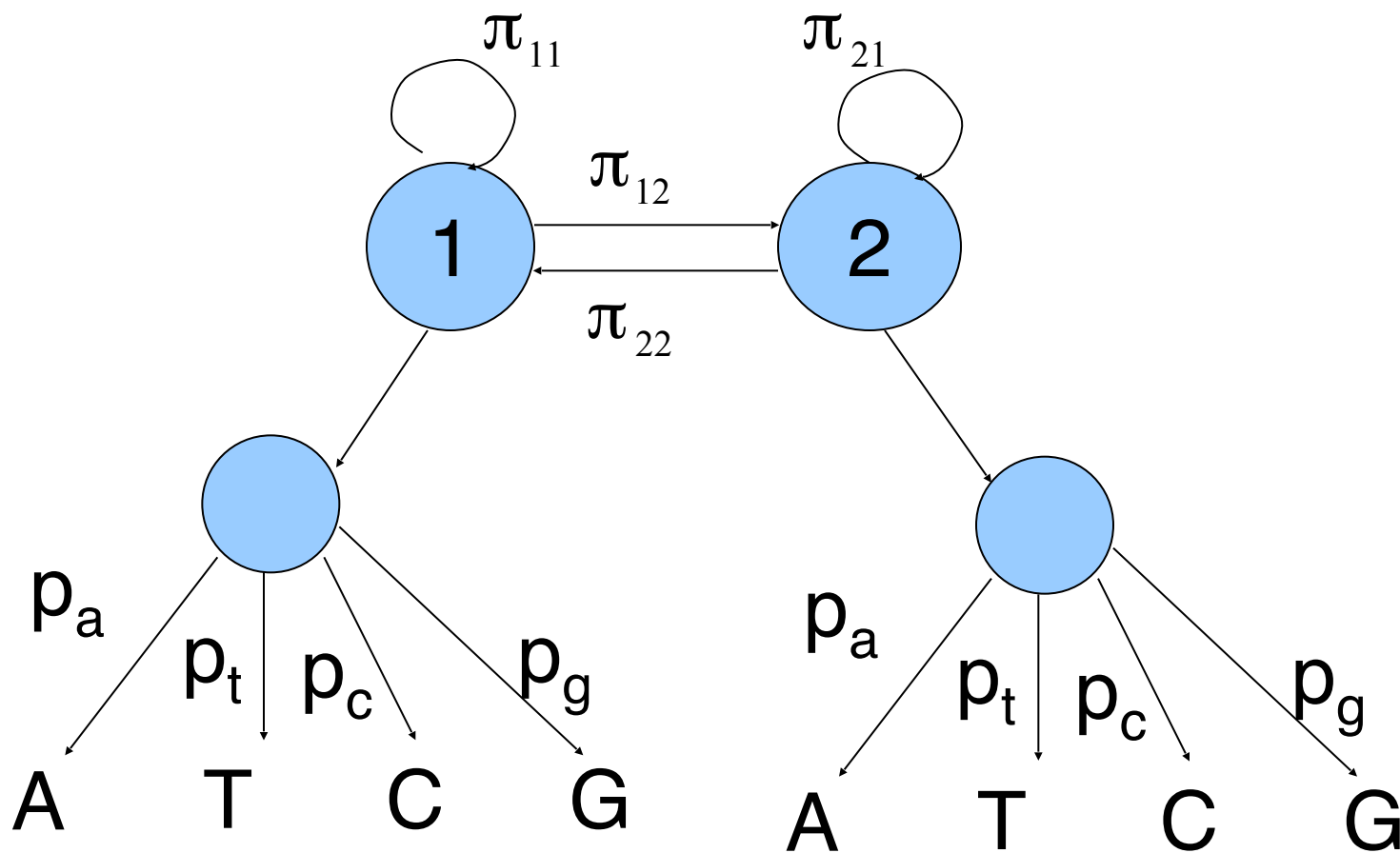
# Mixture model



# Mixture model

- According to probabilities,  $\pi_1$  and  $\pi_2$  each time one of two joined models is selected to generate a character
- Created characters are collected to form an atcg sequence

# Hidden Markov model



# Transition probability

$$\Pi = \begin{bmatrix} \pi_{11} & \pi_{12} \\ \pi_{21} & \pi_{22} \end{bmatrix}$$